

Lattice QCD with Machine learning

Akio Tomiya (Assistant prof. in IPUT Osaka)
akio_at_yukawa.kyoto-u.ac.jp



Based on arXiv:
arXiv: 2103.11965,
2205.08860 etc



What am I?

I am a particle physicist, working on lattice QCD.
I want to apply machine learning on it.

My papers

https://scholar.google.co.jp/citations?user=LKVqy_wAAAAJ

Detection of phase transition via convolutional neural networks

A Tanaka, A Tomiya

Journal of the Physical Society of Japan 86 (6), 063001 **Phase transition detection with NN**

Evidence of effective axial $U(1)$ symmetry restoration at high temperature QCD

A Tomiya, G Cossu, S Aoki, H Fukaya, S Hashimoto, T Kaneko, J Noaki, ...

Physical Review D 96 (3), 034509

Axial anomaly at $T > 0$ with Mobius Domain-wall fermions

KAKENHI

PI: Grant-in-Aid for Transformative Research Areas (A)

MLPhYs Foundation of "Machine Learning Physics"
Grant-in-Aid for Transformative Research Areas (A)

Grant-in-Aid for Early-Career Scientists

CI: Grant-in-Aid for Scientific Research (C), etc

Biography

2015 : PhD in Osaka university

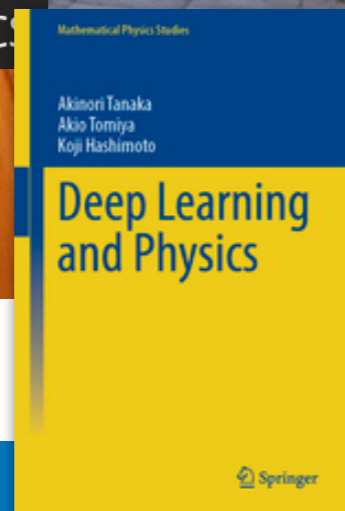
2015 - 2018 : Postdoc in CCNU (Wuhan, China)

2018 - 2021 : SPDR in Riken/BNL (New York, US)

2021 - : Assistant prof. in IPUT Osaka

<https://cometscome.github.io/DLAP2020/>

Deep learning and Physics



Phys + ML

Seminar series: Deep learning and physics

- <https://cometscome.github.io/DLAP2020/>
- Online seminar series since 2020
- Machine learning + Physics
- Thursday morning, bi-weekly

Intensive lecture series

- <https://akio-tomiya.github.io/lectures4mlphys/>
 - #1 An introduction to optimal transport (in Japanese)
 - Wako Riken (Hybrid)
 - Date: 12 Jan (Thu) 13:30-17:00 JST
 - Akinori Tanaka (RIKEN-AIP)

Spring school for computational physics

- https://hohno0223.github.io/comp_phys_spring_school2023/index.html
- @ Okinawa
- Hybrid (we will support traveling fee)
- March 13(Mon)-15(Wed)
- High energy physics + condensed matter + ML + quantum computing, etc

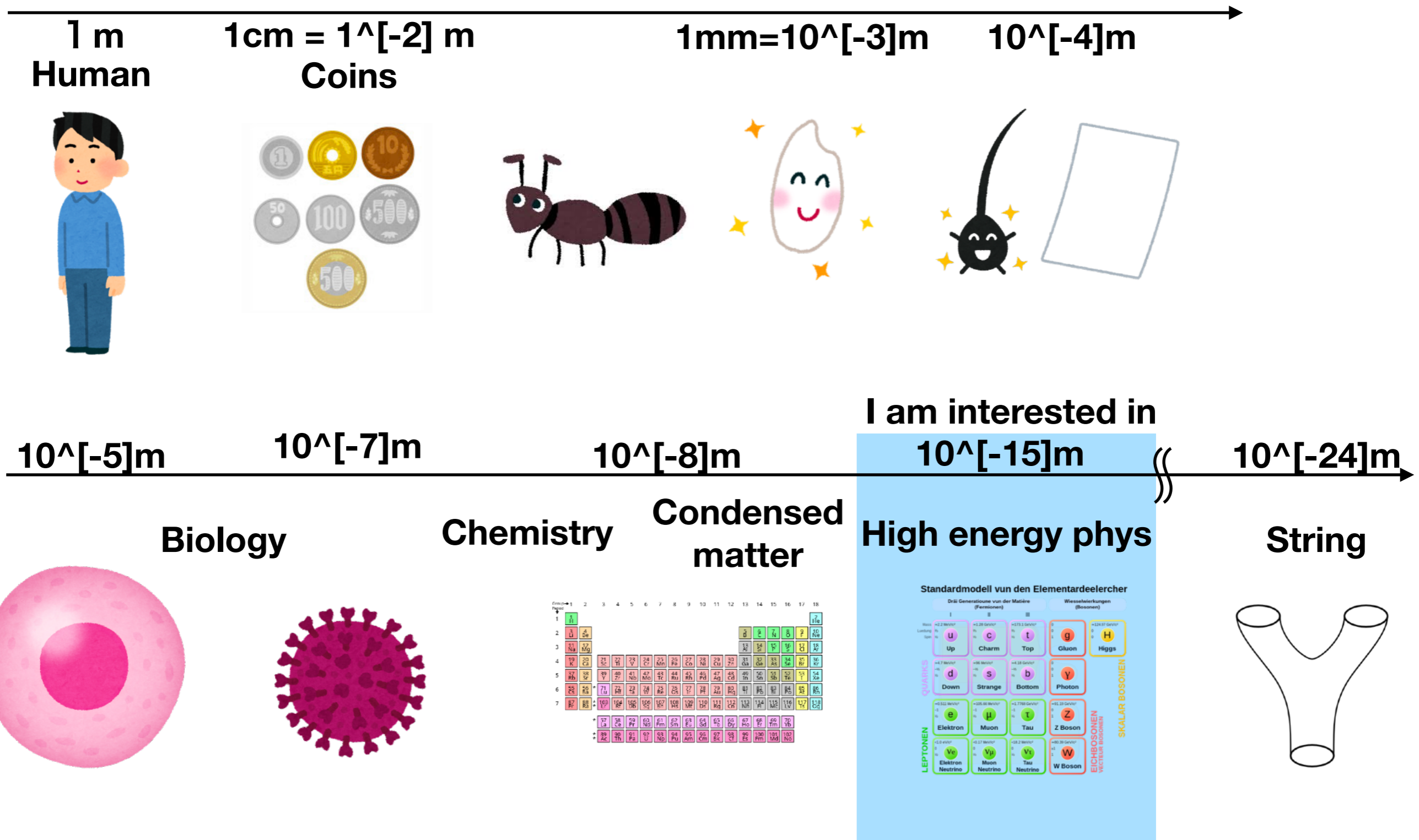
Outline

1. What and why QCD/lattice QCD?
2. Lattice QCD + Machine learning
 1. “Neural net = Smearing”

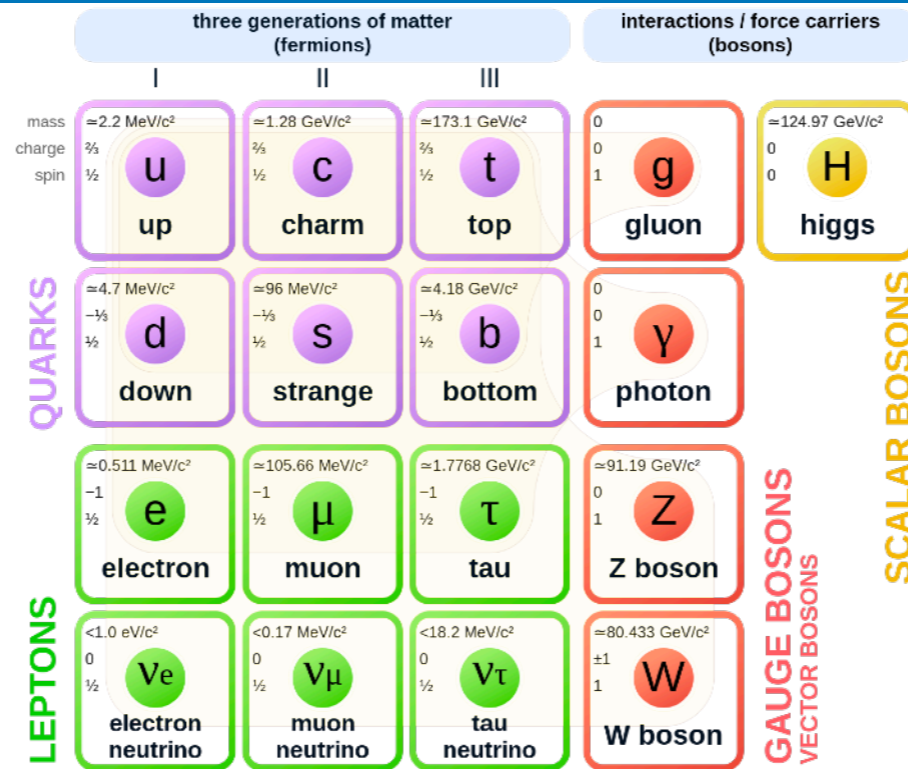
$$\frac{dU_{\mu}^{(t)}(n)}{dt} = \mathcal{G}^{\bar{\theta}}(U_{\mu}^{(t)}(n))$$

Theoretical Physics

Appropriate description depends on the scale



Particle physics = four fundamental forces + matters



- Gravity
 - Binding everything, mediated by graviton(?)
- The electromagnetic force
 - Binding nucleus and electrons, mediated by photon
- The weak force
 - Change particles, mediated by Z, W bosons
- The strong force (very strong)
 - Binding quarks, mediated by gluons

Introduction

QCD: a fundamental theory of particles inside of nuclei

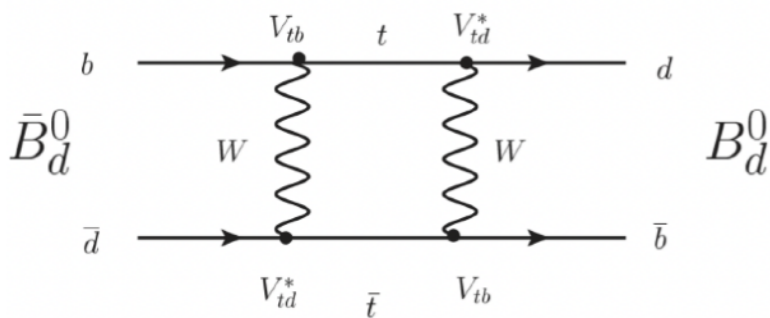
QCD (Quantum Chromo-dynamics) in 3 + 1 dimension

$$S = \int d^4x \left[-\frac{1}{2} \text{tr} F_{\mu\nu} F^{\mu\nu} + \bar{\psi} (i\cancel{\partial} + gA - m) \psi \right]$$

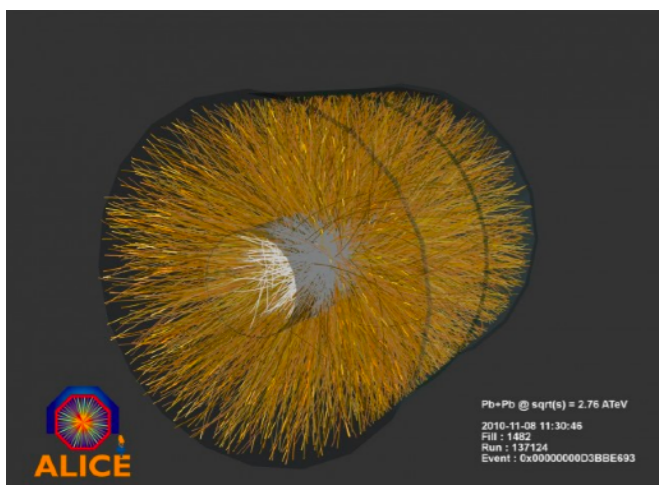
$$F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu - ig[A_\mu, A_\nu]$$

$$|\psi(t)\rangle = e^{-iHt} |\psi(0)\rangle$$

Expectation values with this are needed



- QCD is theory for the strong force and an extension of electro-magnetism
- QCD enables us to calculate (in principle):
 - Equation of state of neutron star, T_c
 - Scattering of quarks and gluons
 - Hadron spectrum (bound state energy of quarks)
- Strongly coupled quantum system
- Use lattice formulation + Monte-Carlo



Lattice path integral > 1000 dim, Trapezoidal int is impossible

K. Wilson 1974

Imaginary time
 $t = -i\tau$

$$S = \int d^4x \left[+ \frac{1}{2} \text{tr} F_{\mu\nu} F_{\mu\nu} + \bar{\psi} (\not{D} - igA + m) \psi \right]$$

Lattice regularization
 $U_\mu = e^{aigA_\mu} \in SU(3)$

$$S[U, \psi, \bar{\psi}] = a^4 \sum_n \left[- \frac{1}{g^2} \text{Re tr} U_{\mu\nu} + \bar{\psi} (\not{D} + m) \psi \right] \quad \text{cutoff} = a^{-1}$$

Both S give same expectation value for long range $\text{Re} U_{\mu\nu} \sim \frac{-1}{2} g^2 a^4 F_{\mu\nu}^2 + O(a^6)$

Quantum expectation values = multi-dimensional integral (Path integral)

$$\langle \mathcal{O} \rangle = \frac{1}{Z} \int \mathcal{D}U \mathcal{D}\bar{\psi} \mathcal{D}\psi e^{-S} \mathcal{O}(U) = \frac{1}{Z} \int \mathcal{D}U e^{-S_{\text{gauge}}[U]} \det(D + m) \mathcal{O}(U)$$

$$= \frac{1}{Z} \int \mathcal{D}U e^{-S_{\text{eff}}[U]} \mathcal{O}(U) \quad S_{\text{eff}}[U] = S_{\text{gauge}}[U] - \log \det(\not{D}[U] + m)$$

$$= \prod_{n \in \{\mathbb{Z}/L\}^4} \prod_{\mu=1}^4 dU_\mu(n)$$

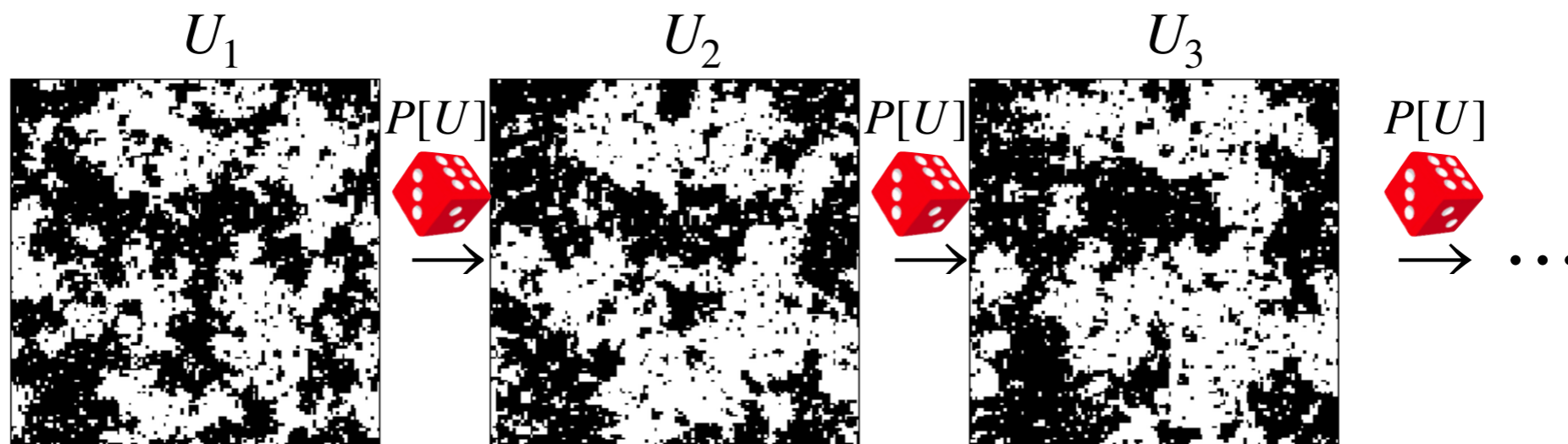
>1000 dim. We cannot use Newton-Cotes type integral like Trapezoid, Simpson etc. We cannot control numerical error

Monte-Carlo integration is available

M. Creutz 1980

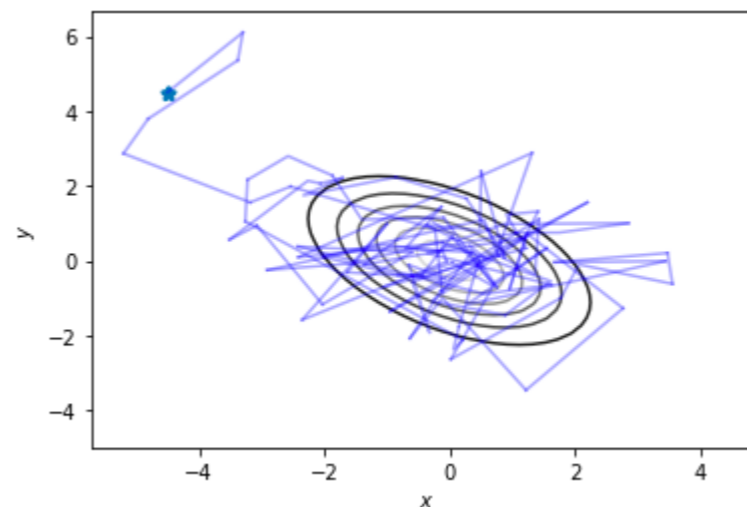
$$\langle \mathcal{O} \rangle = \frac{1}{Z} \int \mathcal{D}U e^{-S_{\text{eff}}[U]} \mathcal{O}(U) \quad S_{\text{eff}}[U] = S_{\text{gauge}}[U] - \log \det(\mathcal{D}[U] + m)$$

Monte-Carlo: Generate field configurations with “ $P[U] \propto e^{-S_{\text{eff}}[U]}$ ”. It gives expectation values



HMC: Hybrid (Hamiltonian) Monte-Carlo
De-facto standard algorithm

$$S(x, y) = \frac{1}{2}(x^2 + y^2 + xy)$$

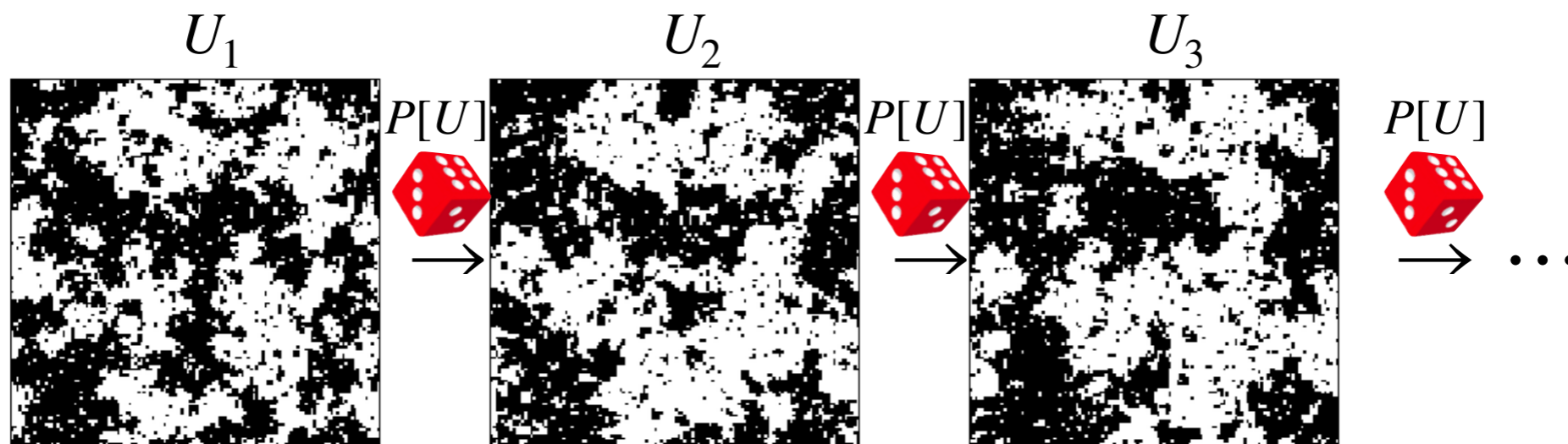


Monte-Carlo integration is available

M. Creutz 1980

$$\langle \mathcal{O} \rangle = \frac{1}{Z} \int \mathcal{D}U e^{-S_{\text{eff}}[U]} \mathcal{O}(U) \quad S_{\text{eff}}[U] = S_{\text{gauge}}[U] - \log \det(\mathcal{D}[U] + m)$$

Monte-Carlo: Generate field configurations with “ $P[U] \propto e^{-S_{\text{eff}}[U]}$ ”. It gives expectation values



Error of integration is determined by the number of sampling

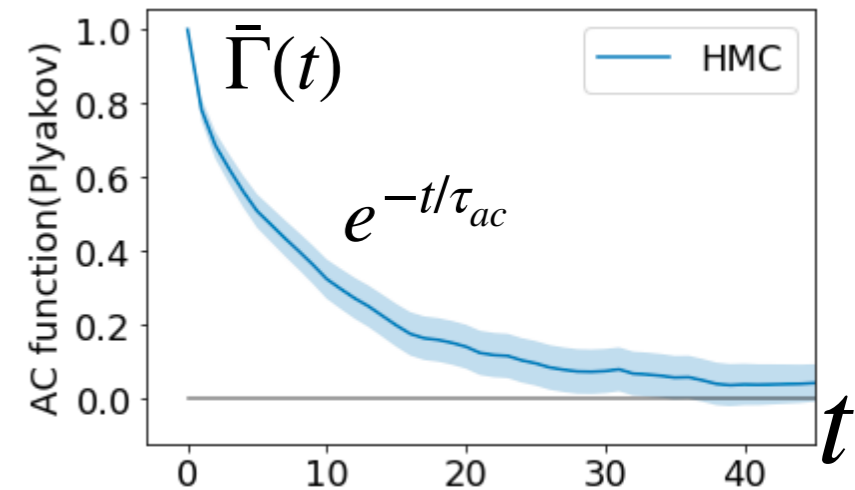
$$\langle \mathcal{O} \rangle = \frac{1}{N_{\text{sample}}} \sum_k^{N_{\text{sample}}} \mathcal{O}[U_k] \pm O\left(\frac{1}{\sqrt{N_{\text{sample}}}}\right)$$

Introduction

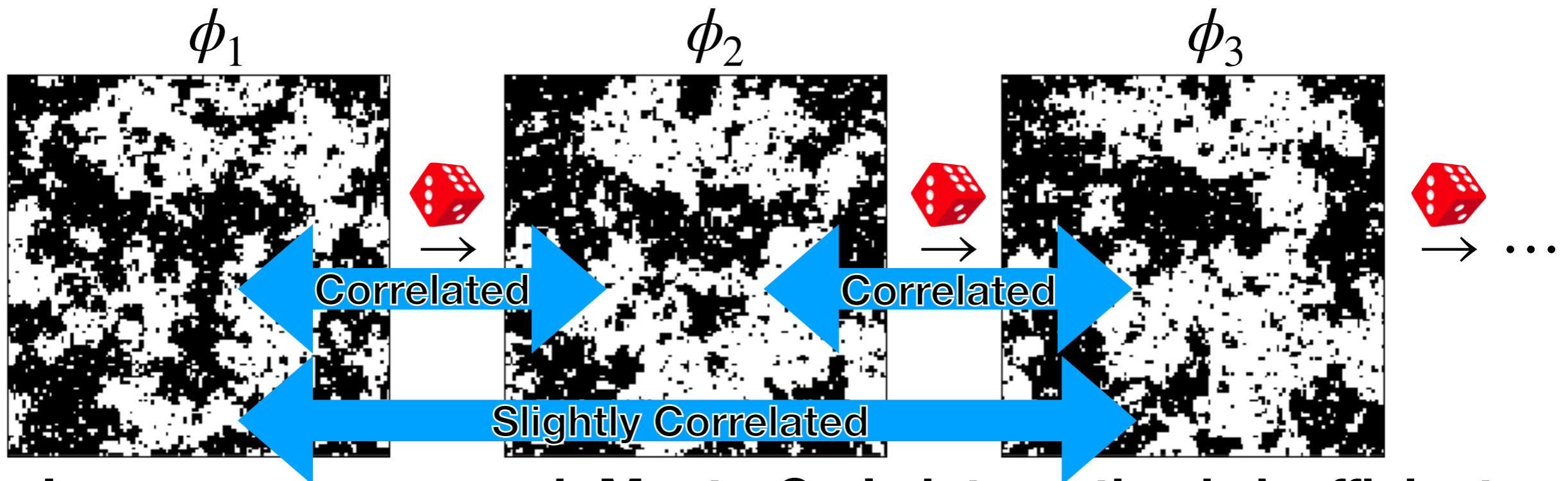
Correlation between samples = inefficiency of calculation

$$\langle O[\phi] \rangle = \frac{1}{N} \sum_k^N O[\phi_k] \pm O\left(\frac{1}{\sqrt{N_{\text{indep}}}}\right)$$

$$N_{\text{indep}} = \frac{N_{\text{sample}}}{2\tau_{ac}}$$



$$\bar{\Gamma}(t) = \frac{1}{N-t} \sum_k (O[\phi_{k+t}] - \bar{O})(O[\phi_k] - \bar{O}) \sim e^{-t/\tau_{ac}}$$



Large τ_{ac} means, such Monte-Carlo integration is inefficient

Introduction

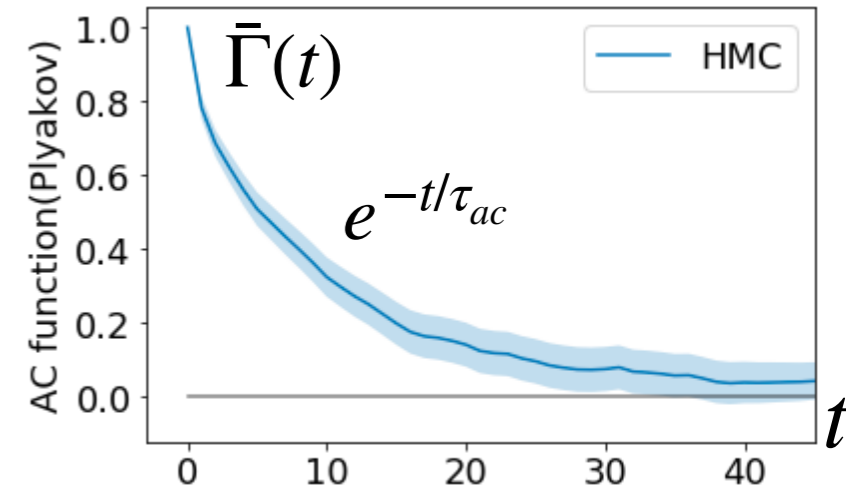
Summary for now: long autocorrelation = inefficiency

$$\langle O[\phi] \rangle = \frac{1}{N} \sum_k^N O[\phi_k] \pm O\left(\frac{1}{\sqrt{N_{\text{indep}}}}\right)$$

$$N_{\text{indep}} = \frac{N_{\text{sample}}}{2\tau_{ac}}$$

$$\bar{\Gamma}(t) = \frac{1}{N-t} \sum_k (O[\phi_{k+t}] - \bar{O})(O[\phi_k] - \bar{O}) \sim e^{-t/\tau_{ac}}$$

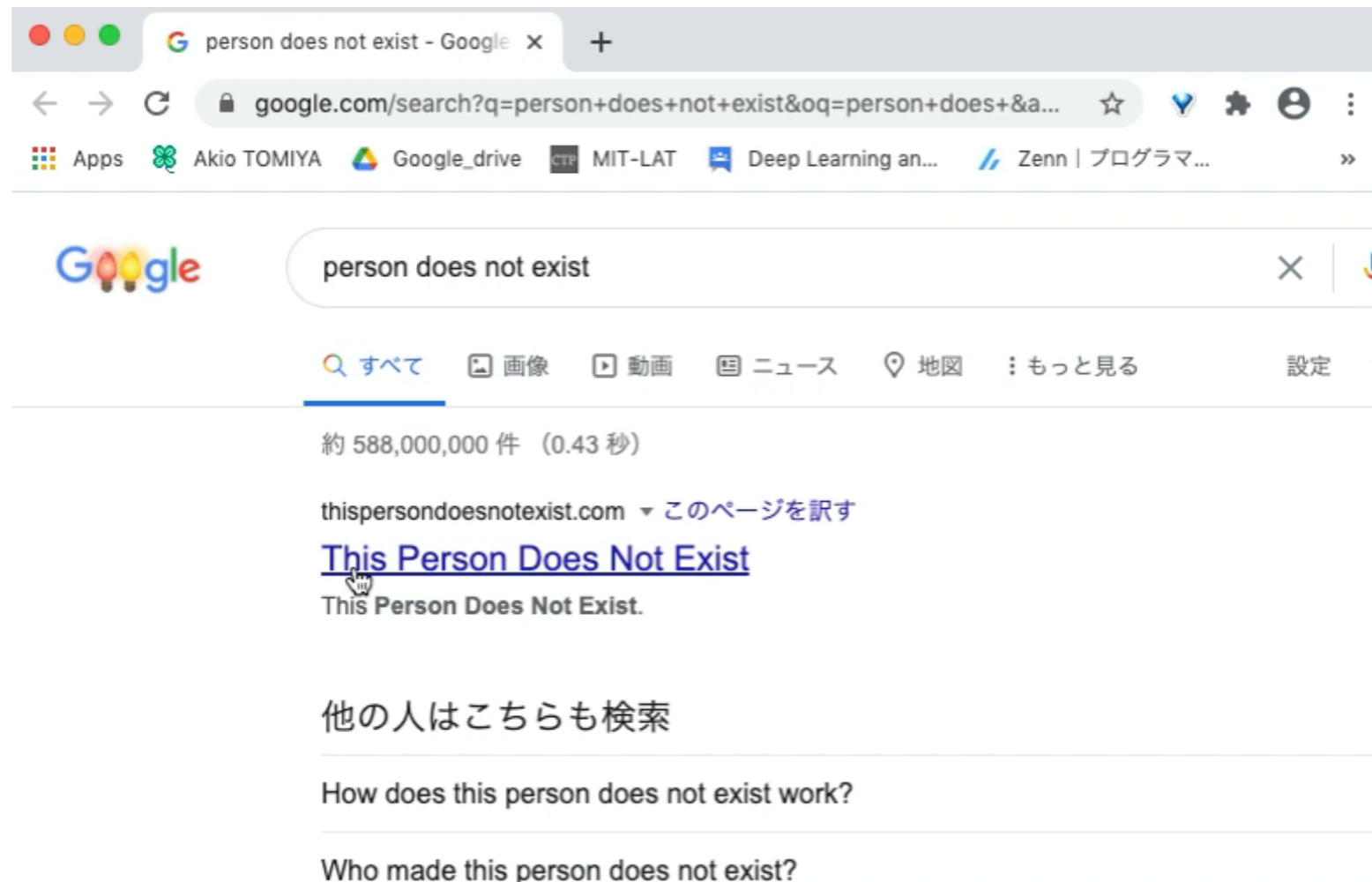
τ_{ac} is given by an update algorithm (N. Madras et. al 1988)



- Autocorrelation time τ_{ac} quantifies similarity between samples
- τ_{ac} is algorithm dependent quantity
- If τ_{ac} becomes half, we can get doubly precise results in the same time cost

Can we make this mild using machine learning?

Neural net can make human face images



Neural net can make human face images

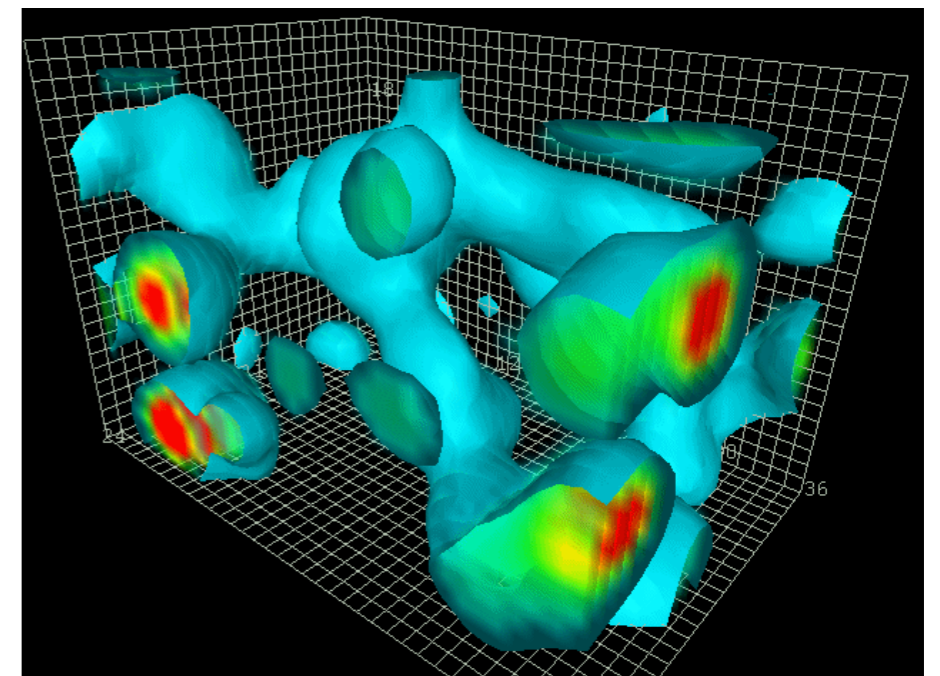
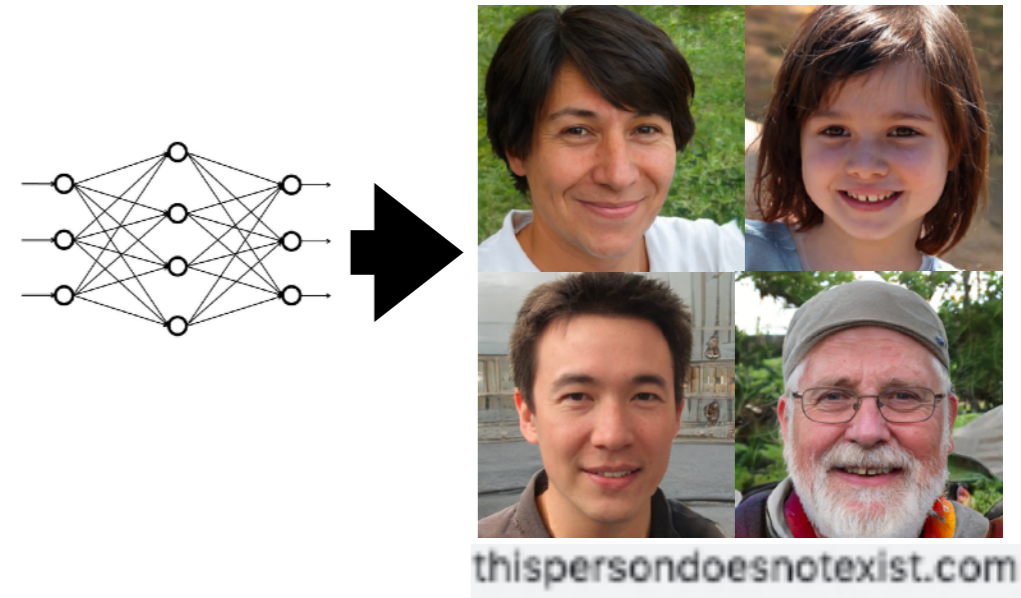
Neural nets can generate realistic human faces (Style GAN2)



Realistic Images can be generated by machine learning!
Configurations as well? (configuration ~ images?)

ML for LQCD is needed

- Machine learning/ Neural networks
 - Data processing techniques for 2d image in daily life (pictures = pixels = a set of real #)
 - Neural network can generate images! (approximately)
- Lattice QCD is more complicated than pictures
 - 4 dimension
 - **Non-abelian gauge d.o.f. and symmetry**
 - Fermions
 - Exactness of algorithm is necessary
- Q. How can we deal with?



<http://www.physics.adelaide.edu.au/theory/staff/leinweber/VisualQCD/QCDvacuum/>

Configuration generation with machine learning is developing

| Year | Group | ML | Dim. | Theory | Gauge sym | Exact? | Fermion? | Reference |
|-------------|-----------------------------|--------------|-----------|--------------|------------------|------------|-----------------------|--------------------|
| 2017 | AT, Akinori Tanaka | RBM + HMC | 2d | Scalar | - | No | No | arXiv: 1712.03893 |
| 2018 | K. Zhou+ | GAN | 2d | Scalar | - | No | No | arXiv: 1810.12879 |
| 2018 | J. Pawłowski + | GAN +HMC | 2d | Scalar | - | Yes? | No | arXiv: 1811.03533 |
| 2019 | MIT+ | Flow | 2d | Scalar | - | Yes | No | arXiv: 1904.12072 |
| 2020 | MIT+ | Flow | 2d | U(1) | Equivariant | Yes | No | arXiv: 2003.06413 |
| 2020 | MIT+ | Flow | 2d | SU(N) | Equivariant | Yes | No | arXiv: 2008.05456 |
| 2020 | AT, Akinori Tanaka + | SLMC | 4d | SU(N) | Invariant | Yes | Partially | arXiv: 2010.11900 |
| 2021 | M. Medvidović+ | A-NICE | 2d | Scalar | - | No | No | arXiv: 2012.01442 |
| 2021 | S. Foreman | L2HMC | 2d | U(1) | Yes | Yes | No | |
| 2021 | AT+ | SLHMC | 4d | QCD | Covariant | Yes | YES! | This talk |
| 2021 | L. Del Debbio+ | Flow | 2d | Scalar, O(N) | - | Yes | No | |
| 2021 | MIT+ | Flow | 2d | Yukawa | - | Yes | Yes | |
| 2021 | S. Foreman, AT+ | Flowed HMC | 2d | U(1) | Equivariant | Yes | No but compatible | arXiv: 2112.01586 |
| 2021 | XY Jing | Neural net | 2d | U(1) | Equivariant | Yes | No | |
| 2022 | J. Finkenrath | Flow | 2d | U(1) | Equivariant | Yes | Yes (diagonalization) | arxiv: 2201.02216 |
| 2022 | MIT+ | Flow | 2d, 4d | U(1), QCD | Equivariant | Yes | Yes | arXiv:2202.11712 + |
| 2022 | AT+ | Flow | 2d, 3d | Scalar | | Yrs | | |

+ ...

LQCD + Machine learning

How to deal gauge sym.

Introduction

Neural network is a universal approximator of functions

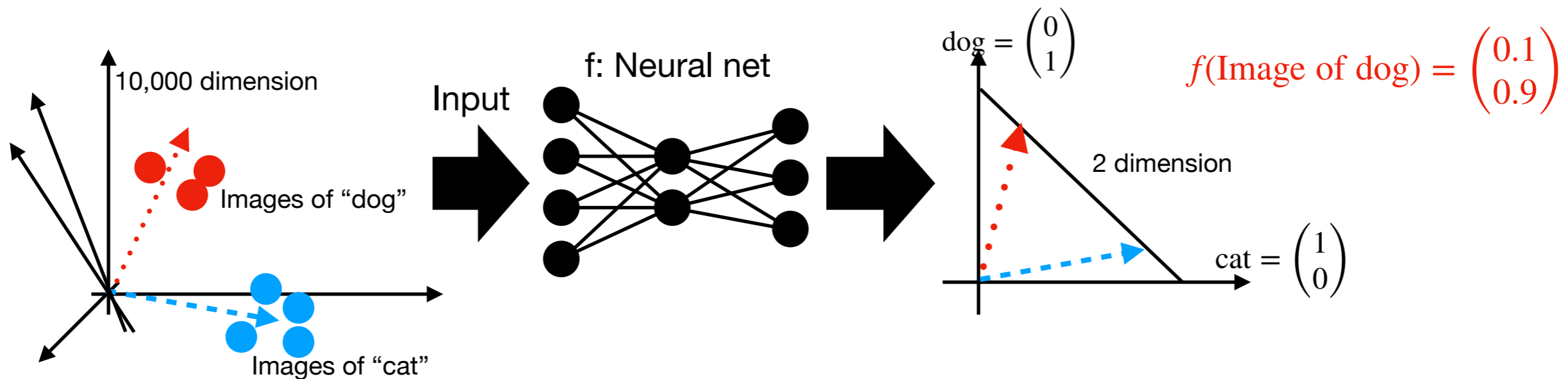
Image classification, cats and dogs

100x100



Flatten \Rightarrow $\begin{pmatrix} 0.000 \\ 0.000 \\ 0.8434 \\ 0.756 \\ 0.3456 \\ \vdots \end{pmatrix}$ Image is a vector
(this is 10,000 dimension)

$\text{dog} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ Label is 2 dim vector
(cat = $(1, 0)^t$)



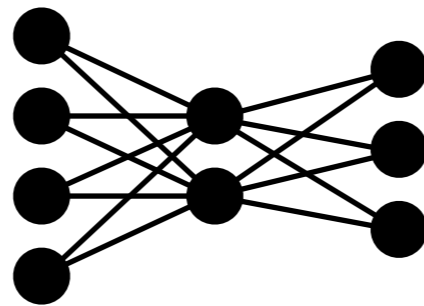
Introduction

Affine transformation + element-wise transformation

Fully connected neural networks

$$f_{\theta}(\vec{x}) = \sigma^{(l=2)}(W^{(l=2)}\sigma^{(l=1)}(W^{(l=1)}\vec{x} + \vec{b}^{(l=1)}) + \vec{b}^{(l=2)})$$

θ represents a set of parameters: eg $w_{ij}^{(l)}, b_i^{(l)}, \dots$ (throughout this talk!)



Component of neural net: $l = 2, 3, \dots$ and $\vec{u}^{(1)} = \vec{x}$

$$\begin{cases} z_i^{(l)} = \sum_j w_{ij}^{(l)} u_j^{(l-1)} + b_i^{(l)} \\ u_i^{(l)} = \sigma^{(l)}(z_i^{(l)}) \end{cases}$$

Matrix product
vector addition
(w, b determined in
the training)

element-wise (**local**)
Non-linear transf.
Typically $\sigma \sim \tanh$ shape

Neural network = (Variational) map between vector to vector

Introduction

Neural network is a universal approximator of functions

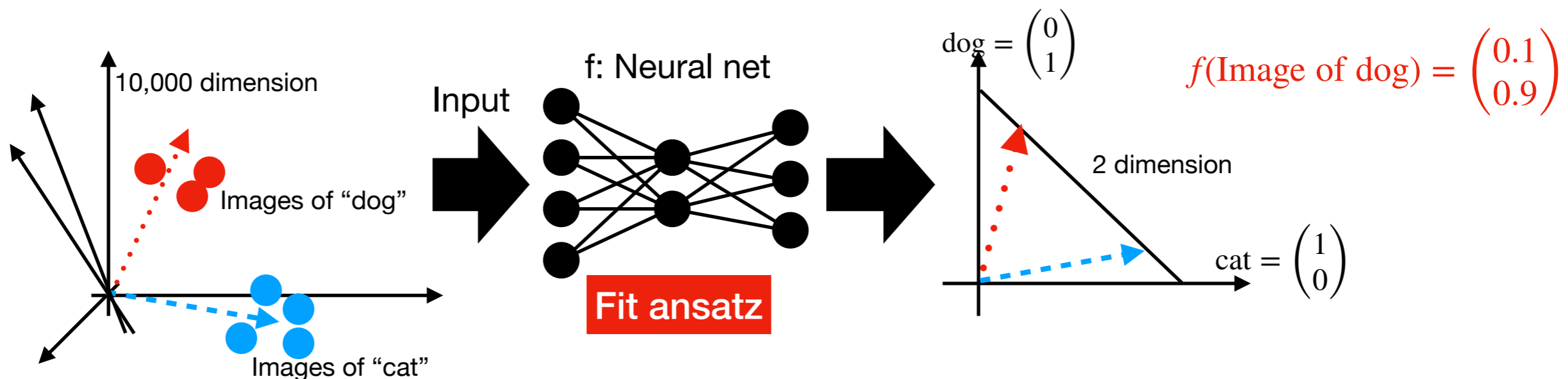
Image classification, cats and dogs

100x100



Flatten \Rightarrow $\begin{pmatrix} 0.000 \\ 0.000 \\ 0.8434 \\ 0.756 \\ 0.3456 \\ \vdots \end{pmatrix}$ Image is a vector
(this is 10,000 dimension)

dog = $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$ Label is 2 dim vector
(cat = $(1, 0)^t$)



Fact: neural network can mimic any function! (universal app. thm)

In this example, neural net mimics a map between image (10,000-dim vector) and label (2-dim vector)

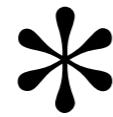
What is the neural networks?

Convolution layer = trainable filter

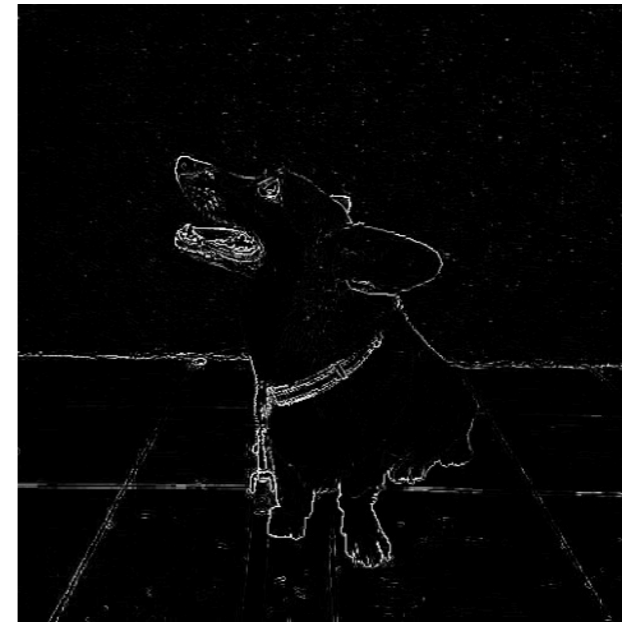
Filter on image



Laplacian filter



| | | |
|---|----|---|
| 0 | 1 | 0 |
| 1 | -2 | 1 |
| 0 | 1 | 0 |



Edge detection

(Discretization of ∂^2)

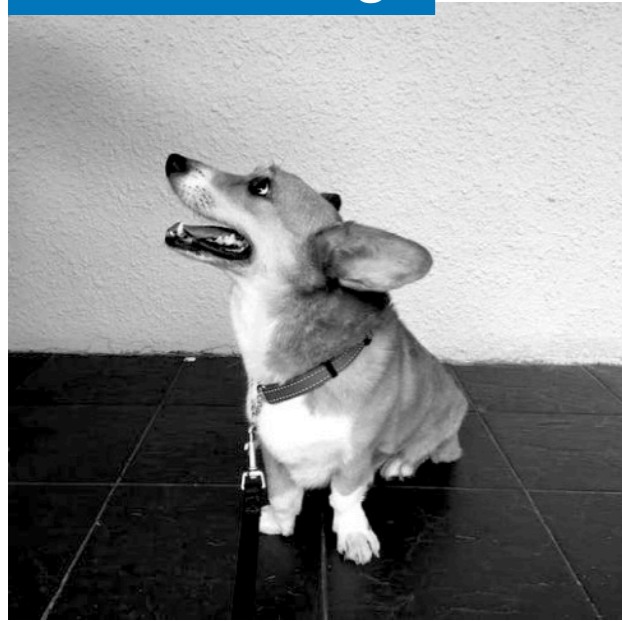
Fact: If inputs are shifted to right, outputs are shifted to right

= translationally equivariant (similar to covariance, operations just commute each other)

What is the neural networks?

Convolution layer = trainable filter

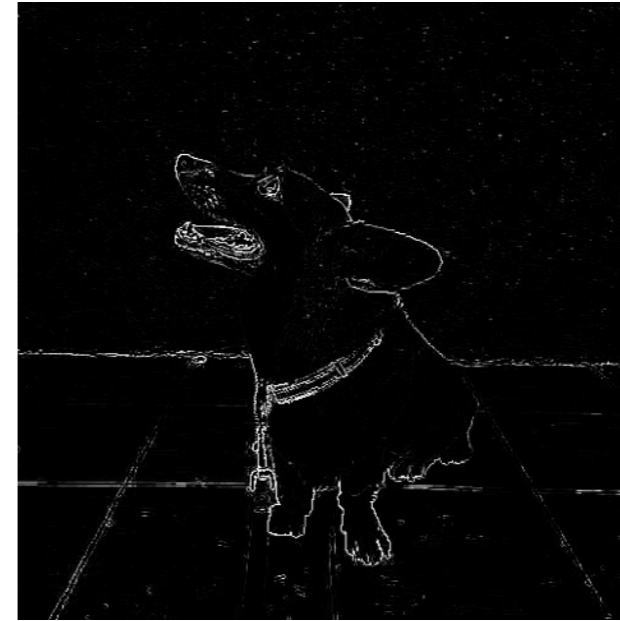
Filter on image



Laplacian filter

$$\begin{matrix} * & & \\ & \begin{matrix} 0 & 1 & 0 \\ 1 & -2 & 1 \\ 0 & 1 & 0 \end{matrix} & = \\ & & \end{matrix}$$

(Discretization of ∂^2)

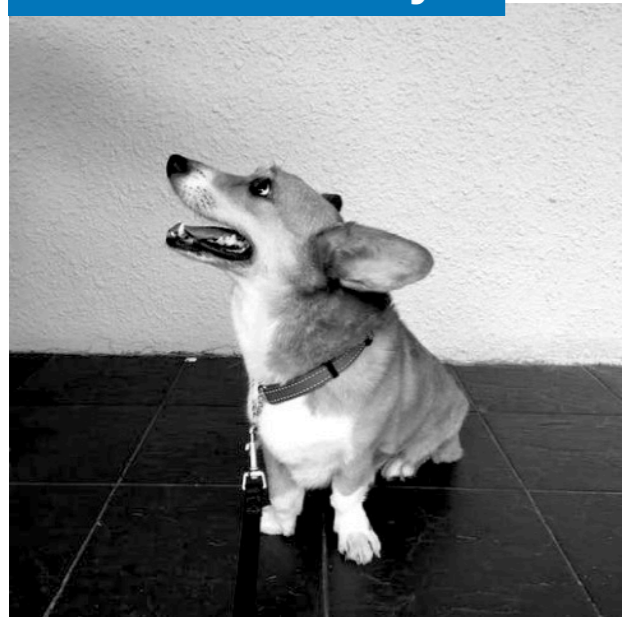


Edge detection

Fact: If inputs are shifted to right, outputs are shifted to right

= translationally equivariant (similar to covariance, operations just commute each other)

Convolution layer



Trainable filter

$$\begin{matrix} * & & \\ & \begin{matrix} W_{11} & W_{12} & W_{13} \\ W_{21} & W_{22} & W_{23} \\ W_{31} & W_{32} & W_{33} \end{matrix} & \longrightarrow \\ & & \end{matrix}$$

Edge detection

Smoothing
(Gaussian filter)

...

Fukushima, Kunihiko (1980)
Zhang, Wei (1988) + a lot!

Gaussian filter

$$\frac{1}{16} \begin{matrix} \begin{matrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{matrix} \end{matrix}$$

This can be any filter which helps feature extraction but still translationally equivariant!

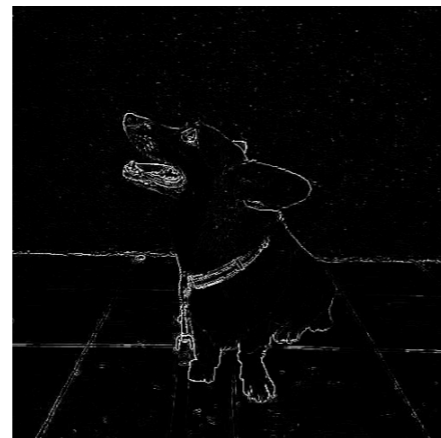
Convolution neural network

Training can be done with back propagation

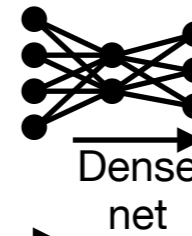
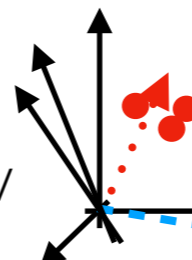


| | | |
|----------|----------|----------|
| W_{11} | W_{12} | W_{13} |
| W_{21} | W_{22} | W_{23} |
| W_{31} | W_{32} | W_{33} |

Translation equivariant map with trainable parameters



G.A.
Pooling/
flatten



dog = $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$

cat = $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$

loss function quantifies error of output

feed L

Feedback = training (Steepest descent)

Smearing

Smoothing improves global properties

Eg.

Coarse image



Numerical derivative is unstable

Gaussian filter

$$\frac{1}{16}$$

| | | |
|---|---|---|
| 1 | 2 | 1 |
| 2 | 4 | 1 |
| 1 | 2 | 1 |



Smoothened image



Numerical derivative is stable

Smearing

Smoothing improves global properties

Eg.

Coarse image



Numerical derivative is unstable

Gaussian filter

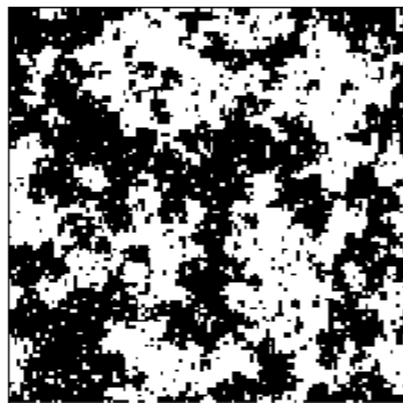
$$\frac{1}{16} \begin{array}{|c|c|c|} \hline 1 & 2 & 1 \\ \hline 2 & 4 & 1 \\ \hline 1 & 2 & 1 \\ \hline \end{array}$$


Smoothened image



Numerical derivative is stable

Gauge configurations have **gauge**, translation, 90 deg rot symmetries



Gauge transformation on the lattice

$$U_\mu(n) \rightarrow g(n)U_\mu(n)g^\dagger(n + \mu) \quad g(n) \in SU(3)$$

$$S[U] \rightarrow S[U]$$

Smoothing improves global properties

Eg.

Coarse image



Numerical derivative is unstable

Gaussian filter

$$\frac{1}{16} \begin{array}{|c|c|c|} \hline 1 & 2 & 1 \\ \hline 2 & 4 & 1 \\ \hline 1 & 2 & 1 \\ \hline \end{array}$$


Smoothened image



Numerical derivative is stable

We want to smoothen gauge configurations with keeping gauge symmetry

Two types:

APE-type smearing

Stout-type smearing

M. Albanese+ 1987
R. Hoffmann+ 2007
C. Morningster+ 2003

Smearing

Smoothing with gauge symmetry, APE type

M. Albanese+ 1987
R. Hoffmann+ 2007

APE-type smearing

$$U_\mu(n) \rightarrow U_\mu^{\text{fat}}(n) = \mathcal{N} \left[(1 - \alpha)U_\mu(n) + \frac{\alpha}{6} V_\mu^\dagger[U](n) \right]$$

Covariant sum

Normalization

$$\mathcal{N}[M] = \frac{M}{\sqrt{M^\dagger M}} \quad \text{Or projection}$$

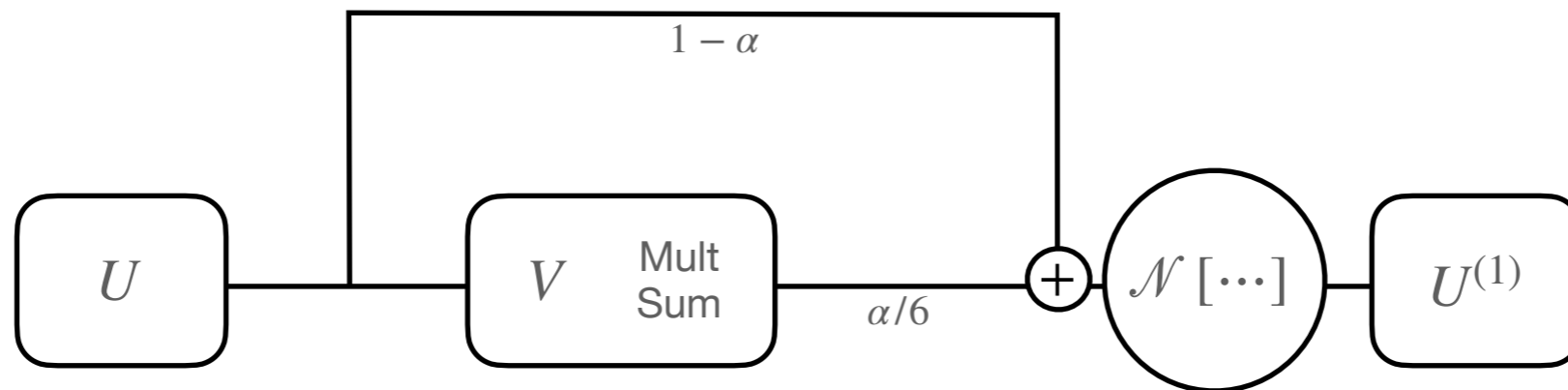
$$V_\mu^\dagger[U](n) = \sum_{\nu \neq \mu} U_\nu(n) U_\mu(n + \hat{\nu}) U_\nu^\dagger(n + \hat{\mu}) + \dots$$

$V_\mu^\dagger[U](n)$ & $U_\mu(n)$ shows same transformation
→ $U_\mu^{\text{fat}}[U](n)$ is as well

Schematically,

$$\Rightarrow \text{fat line} = \mathcal{N} \left[(1 - \alpha) \text{line} + \frac{\alpha}{6} \sum_\nu \text{loop diagrams} \right]$$

In the calculation graph,



Smearing

Smoothing with gauge symmetry, stout type

C. Morningster+ 2003

Stout-type smearing

$$U_\mu(n) \rightarrow U_\mu^{\text{fat}}(n) = e^Q U_\mu(n)$$

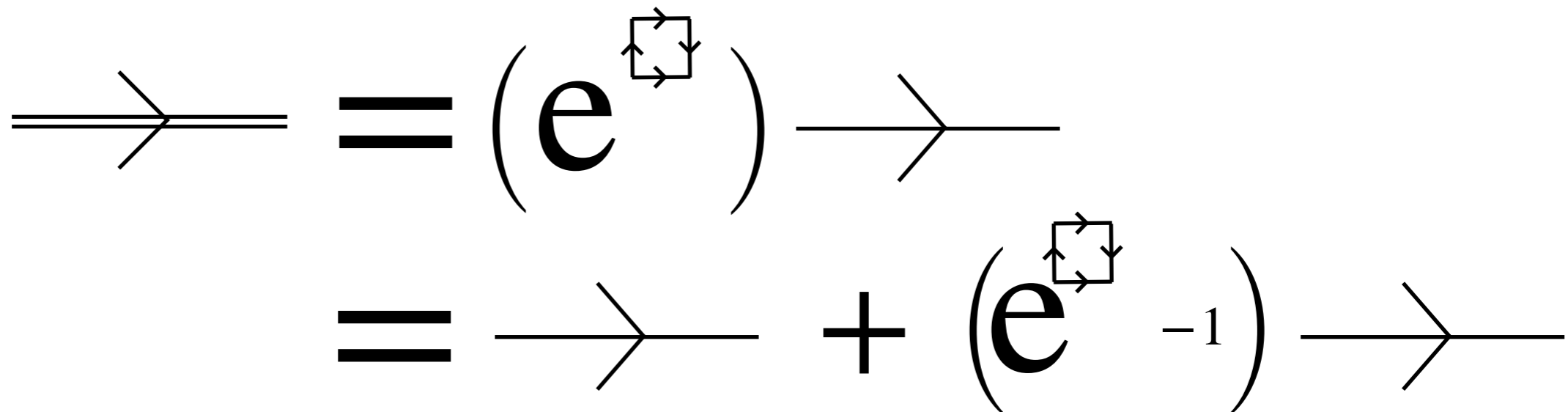
Covariant sum

$$= U_\mu(n) + (e^Q - 1)U_\mu(n)$$

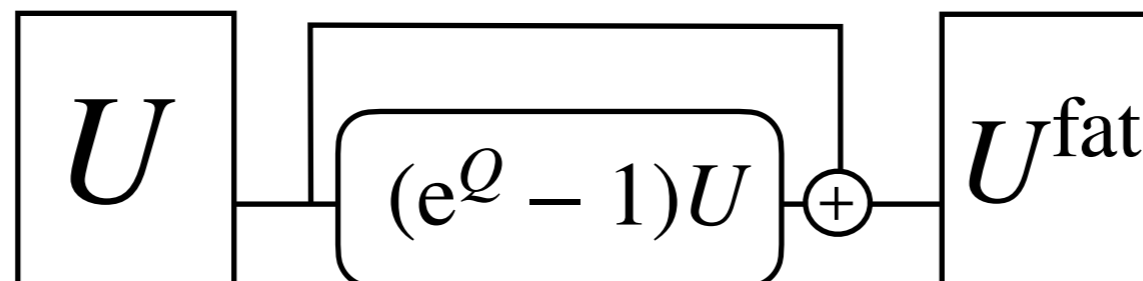
 Q : anti-hermitian traceless plaquette

This is less obvious but this actually obeys same transformation

Schematically,



In the calculation graph,



Smearing

Smearing decomposes into two parts

General form of smearing (covariant transformation)

$$\left\{ \begin{array}{l} z_{\mu}(n) = w_1 U_{\mu}(n) + w_2 \mathcal{G}[U] \\ U_{\mu}^{\text{fat}}(n) = \mathcal{N}(z_{\mu}(n)) \end{array} \right. \quad \begin{array}{l} \text{Gauge covariant sum} \\ \text{A local function} \end{array}$$

Smearing

Smearing \sim neural network with fixed parameter!

AT Y. Nagai arXiv: 2103.11965

General form of smearing (covariant transformation)

$$\left\{ \begin{array}{l} z_{\mu}(n) = w_1 U_{\mu}(n) + w_2 \mathcal{G}[U] \\ U_{\mu}^{\text{fat}}(n) = \mathcal{N}(z_{\mu}(n)) \end{array} \right. \quad \begin{array}{l} \text{Gauge covariant sum} \\ \text{A local function} \end{array}$$

It has similar structure with neural networks,

$$\left\{ \begin{array}{l} z_i^{(l)} = \sum_j w_{ij}^{(l)} u_j^{(l-1)} + b_i^{(l)} \\ u_i^{(l)} = \sigma^{(l)}(z_i^{(l)}) \end{array} \right. \quad \begin{array}{l} \text{Matrix product} \\ \text{vector addition} \\ \\ \text{element-wise (local)} \\ \text{Non-linear transf.} \\ \text{Typically } \sigma \sim \text{tanh shape} \end{array}$$

Actually, we can find a dictionary between them

Gauge covariant neural network

= trainable smearing

AT Y. Nagai arXiv: 2103.11965

Dictionary

| | (convolutional) Neural network | Smearing in LQCD |
|-------------------------------|---|---|
| Input | Image (2d data, structured) | gauge config (4d data, structured) |
| Output | Image (2d data, structured) | gauge config (4d data, structured) |
| Symmetry | Translation | Translation, rotation(90°), Gauge sym. |
| with Fixed param | Image filter | (APE/stout ...) Smearing |
| Local operation | Summing up nearest neighbor with weights | Summing up staples with weights |
| Activation function | Tanh, ReLU, sigmoid, ... | projection/normalization in Stout/HYP/HISQ |
| Formula for chain rule | Backprop | “Smearred force calculations” (Stout) |
| Training? | Backprop + Delta rule | AT Nagai 2103.11965 |

Well-known

(Index i in the neural net corresponds to n & μ in smearing. Information processing with NN is evolution of scalar field)

Takeaway message

Gauge Covariant Neural networks
= trainable smearing, training for $SU(N)$ fields

Gauge covariant neural network = general smearing with trainable parameters w

$$U_{\mu}^{(l+1)}(n) [U^{(l)}] : \begin{cases} z_{\mu}^{(l+1)}(n) = w_1^{(l)} U_{\mu}^{(l)}(n) + w_2^{(l)} \mathcal{G}_{\bar{\theta}}^{(l)} [U] \\ \mathcal{N}(z_{\mu}^{(l+1)}(n)) \end{cases}$$

(Weight “ w ” can be depend on n and μ = fully connected like. Less symmetric, more parameters)

e.g.
$$U_{\mu}^{\text{NN}}(n) [U] = U_{\mu}^{(3)}(n) \left[U_{\mu}^{(2)}(n) \left[U_{\mu}^{(1)}(n) \left[U_{\mu}(n) \right] \right] \right]$$

Good properties: Obvious gauge symmetry. Translation, rotational symmetries.

(Analogous to convolutional layer, this fully uses information of the symmetries)

$$U_{\mu}(n) \mapsto U_{\mu}^{\text{NN}}(n) = U_{\mu}^{\text{NN}}(n) [U]$$

1. Gauge covariant composite function:

Input = gauge field, Output = gauge field

2. Parameters in the network can be trainable using ML techniques.

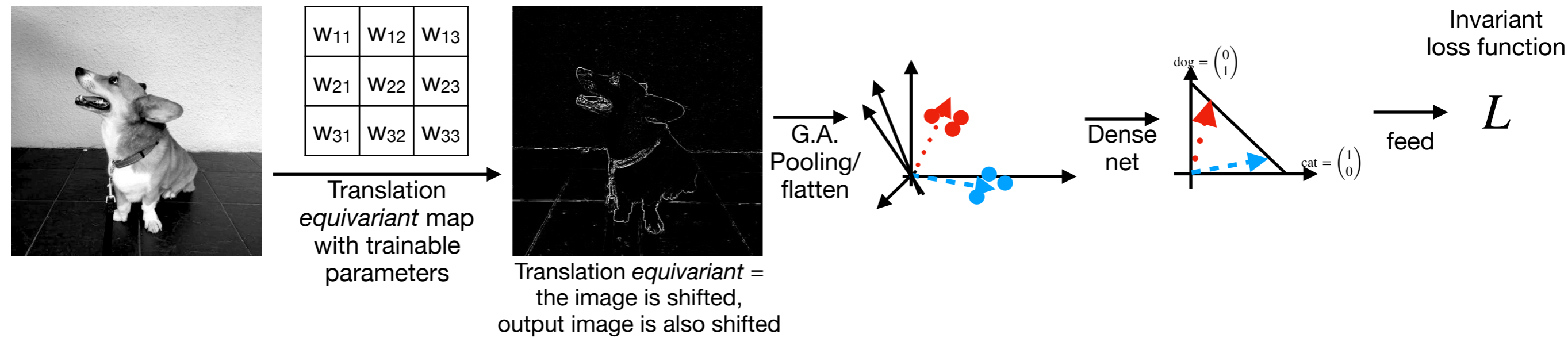
Gauge covariant neural network

Training can be done with (extended) back propagation

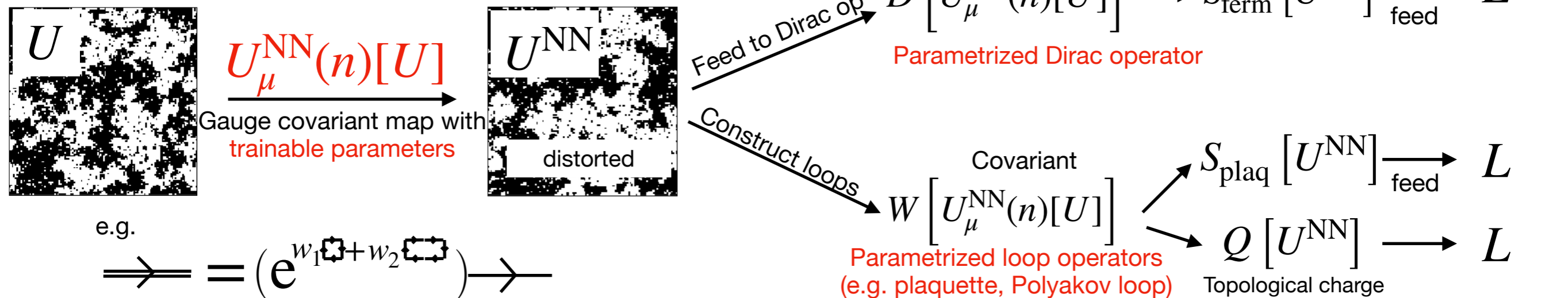
AT Y. Nagai arXiv: 2103.11965

Gauge inv. loss function can be constructed by gauge invariant actions

Usual neural network



Covariant neural networks

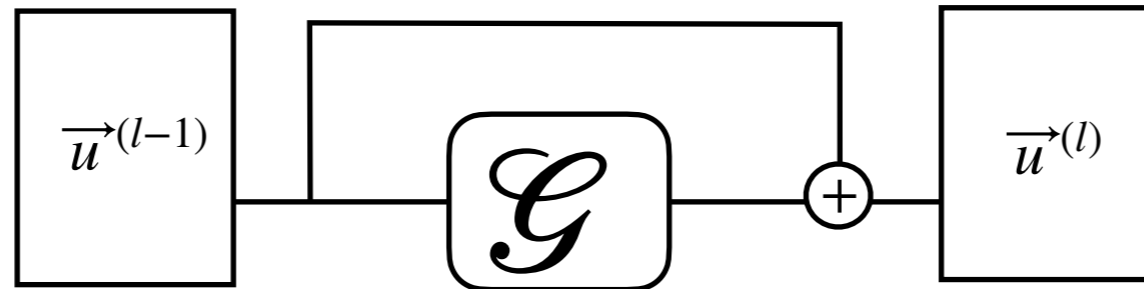


cf. Gauge equivariant neural net (M Favoni+)

Gauge covariant neural network

Neural ODE of Cov-Net = “gradient flow”

ResNet
↓ Continuum Layer Limit
Neural ODE



$$\frac{d\vec{u}^{(t)}}{dt} = \mathcal{G}(\vec{u}^{(t)})$$

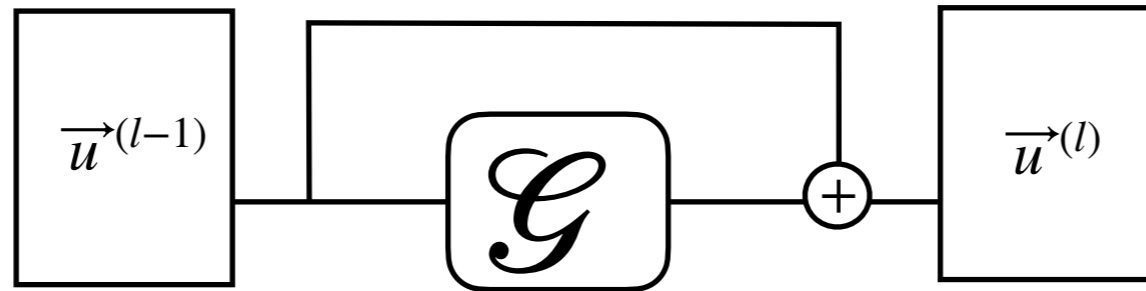
arXiv: 1512.03385

arXiv: 1806.07366
(Neural IPS 2018 best paper)

Gauge covariant neural network

Neural ODE of Cov-Net = “gradient flow”

ResNet



arXiv: 1512.03385

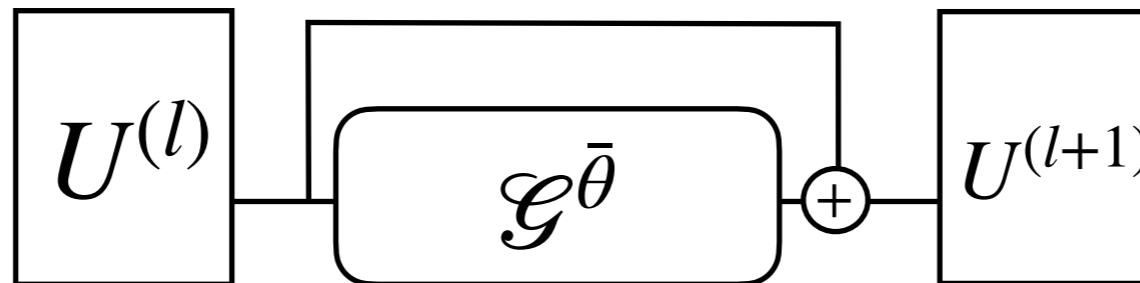
Continuum
Layer
Limit

Neural ODE

$$\frac{d\vec{u}^{(t)}}{dt} = \mathcal{G}(\vec{u}^{(t)})$$

arXiv: 1806.07366
(Neural IPS 2018 best paper)

Gauge-cov net



AT Y. Nagai arXiv: 2103.11965

Continuum
Layer
Limit

Neural ODE

$$\frac{dU_{\mu}^{(t)}(n)}{dt} = \mathcal{G}^{\bar{\theta}}(U_{\mu}^{(t)}(n))$$

“Gradient” flow
(not has to be gradient of S)

for Gauge-cov NN

“Continuous stout smearing is the Wilson flow”

2010 M. Luscher

Gauge covariant neural network

Short summary

| | Symmetry | Fixed parameter | Continuum limit of layers | How to Train |
|---|--|---|---------------------------|---|
| Conventional neural network | Convolution: Translation | Convolution: Filtering (e.g Gaussian/ Laplacian) | ResNet: Neural ODE | Delta rule and backprop Gradient opt. |
| Gauge cov. net <small>AT Y. Nagai arXiv: 2103.11965</small> | Gauge covariance Translation equiv, 90° rotation equiv | Smearing | “Gradient flow” | Extended Delta rule and backprop Gradient opt. |

Re-usable stout
force subroutine
(Implementation is easy &
no need to use ML library)

Next, I show a demonstration

An application

Self-learning HMC

Problems to solve

arXiv: 2103.11965

Our neural network enables us to **parametrize** gauge symmetric action covariant way. **It can be used in variational ansatz in gauge theory.**

e.g.
$$S^{\text{NN}}[U] = S_{\text{plaq}} \left[U_{\mu}^{\text{NN}}(n)[U] \right]$$
$$S^{\text{NN}}[U] = S_{\text{stag}} \left[U_{\mu}^{\text{NN}}(n)[U] \right]$$

Test of our neural network?

Can we mimic a **different** Dirac operator using neural net?

Artificial problem for HMC:

$$\left\{ \begin{array}{l} \text{Target action} \quad S[U] = S_g[U] + S_f[\phi, U; m = 0.3], \\ \text{Action in MD} \quad S_{\theta}[U] = S_g[U] + S_f[\phi, \underline{U_{\theta}^{\text{NN}}[U]}; m_h = 0.4], \end{array} \right.$$

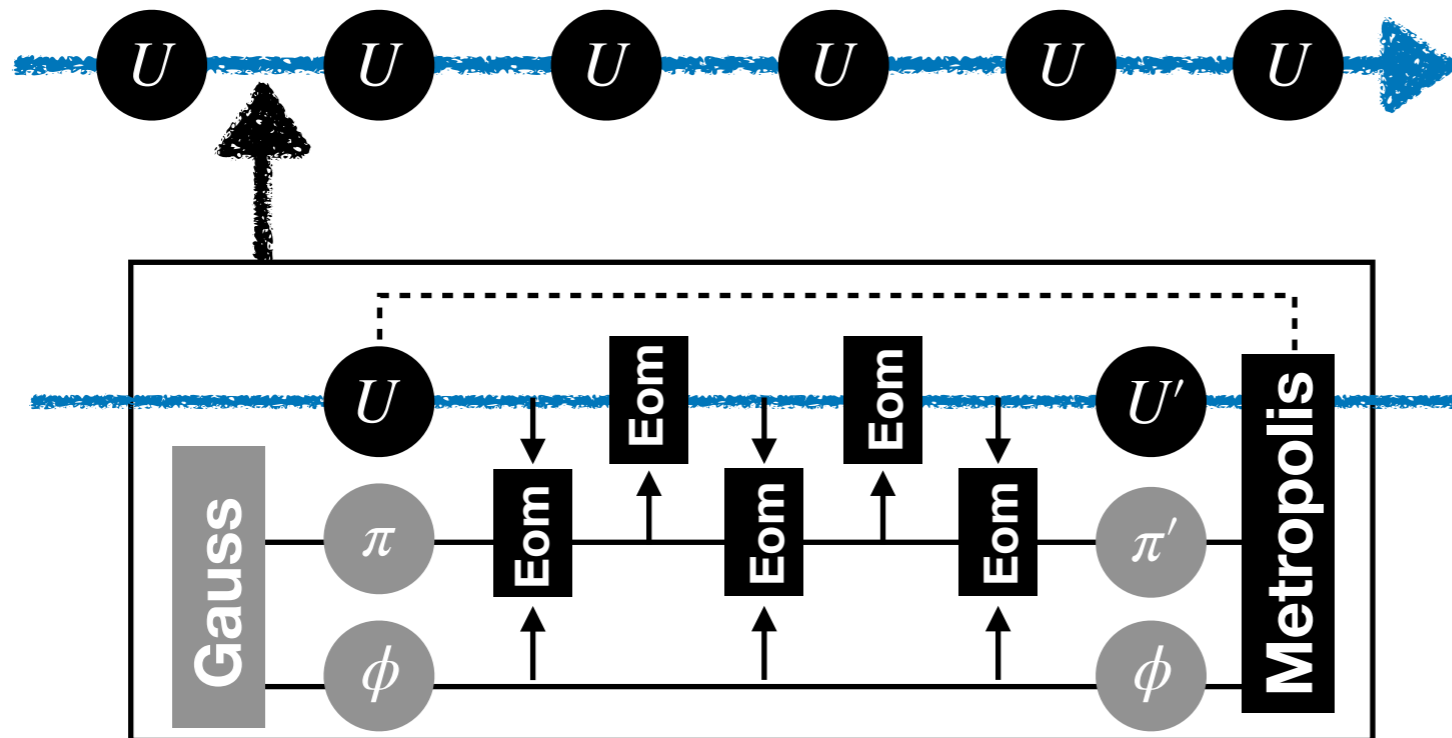
Q. Simulations with approximated action can be exact?
-> Yes! with SLHMC (Self-learning HMC)

SLHMC = Exact algorithm with ML

SLHMC for gauge system with dynamical fermions

arXiv: 2103.11965 and reference therein

HMC



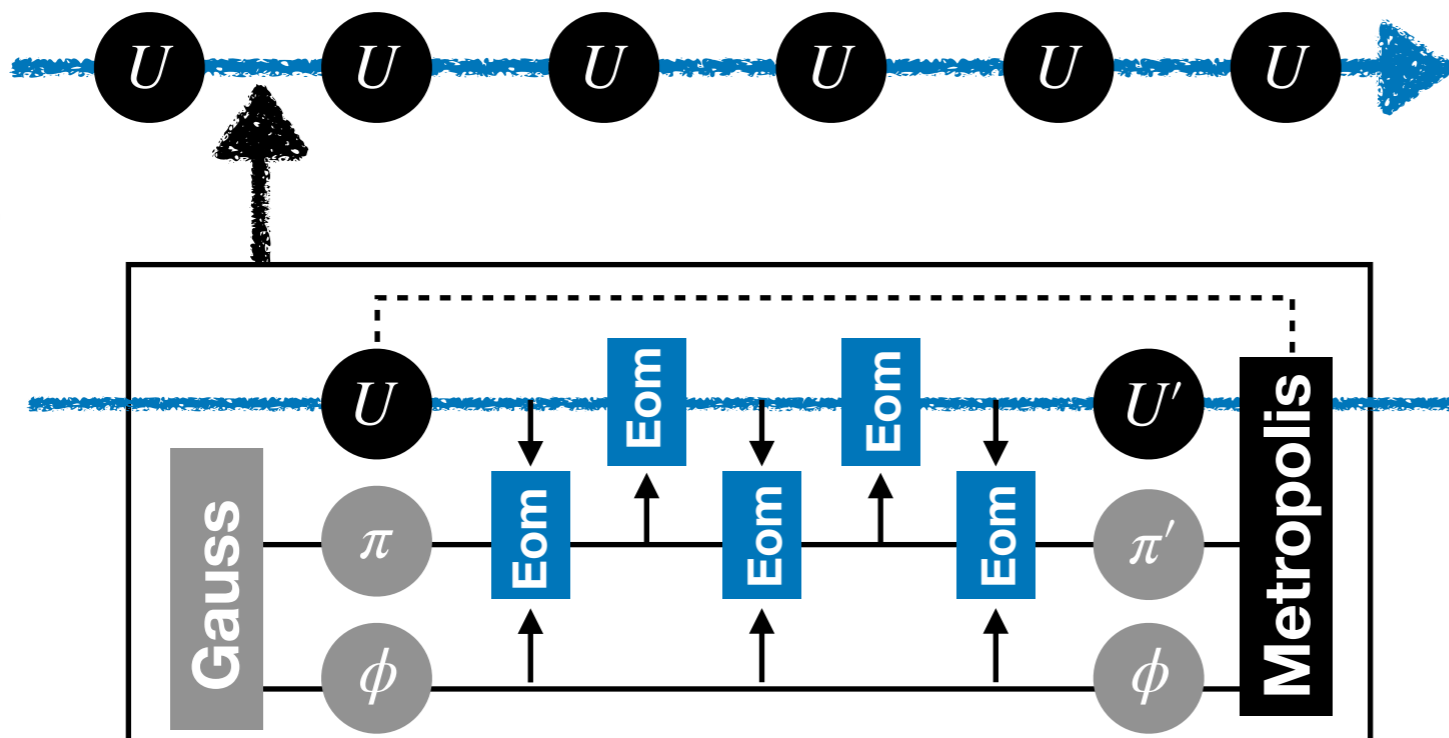
Eom Metropolis

Both use

$$H_{\text{HMC}} = \frac{1}{2} \sum \pi^2 + S_g + S_f$$

Non-conservation of H cancels since the molecular dynamics is reversible

Self Learning HMC



Metropolis

$$H = \frac{1}{2} \sum \pi^2 + S_g + S_f[U]$$

Eom

$$H = \frac{1}{2} \sum \pi^2 + S_g + S_f[U^{\text{NN}}[U]]$$

Neural net approximated fermion action but exact

SLHMC works as an adaptive reweighting!

Application for the staggered in 4d

Akio Tomiya

Lattice setup and question

arXiv: 2103.11965

Target Two color QCD (plaquette + staggered)

Algorithms SLHMC, HMC (comparison)

Parameter Four dimension, L=4, m = 0.3, beta = 2.7, Nf=4 (non-rooting)

Target action $S[U] = S_g[U] + S_f[\phi, U; m = 0.3],$

For Metropolis Test

Action in MD (for SLHMC) $S_\theta[U] = S_g[U] + S_f[\phi, U_\theta^{\text{NN}}[U]; m_h = 0.4],$

Observables Plaquette, Polyakov loop, Chiral condensate $\langle \bar{\psi}\psi \rangle$

Code Full scratch,
fully written in Julia lang.

 **LatticeQCD.jl**

(But we added some functions on the public version)

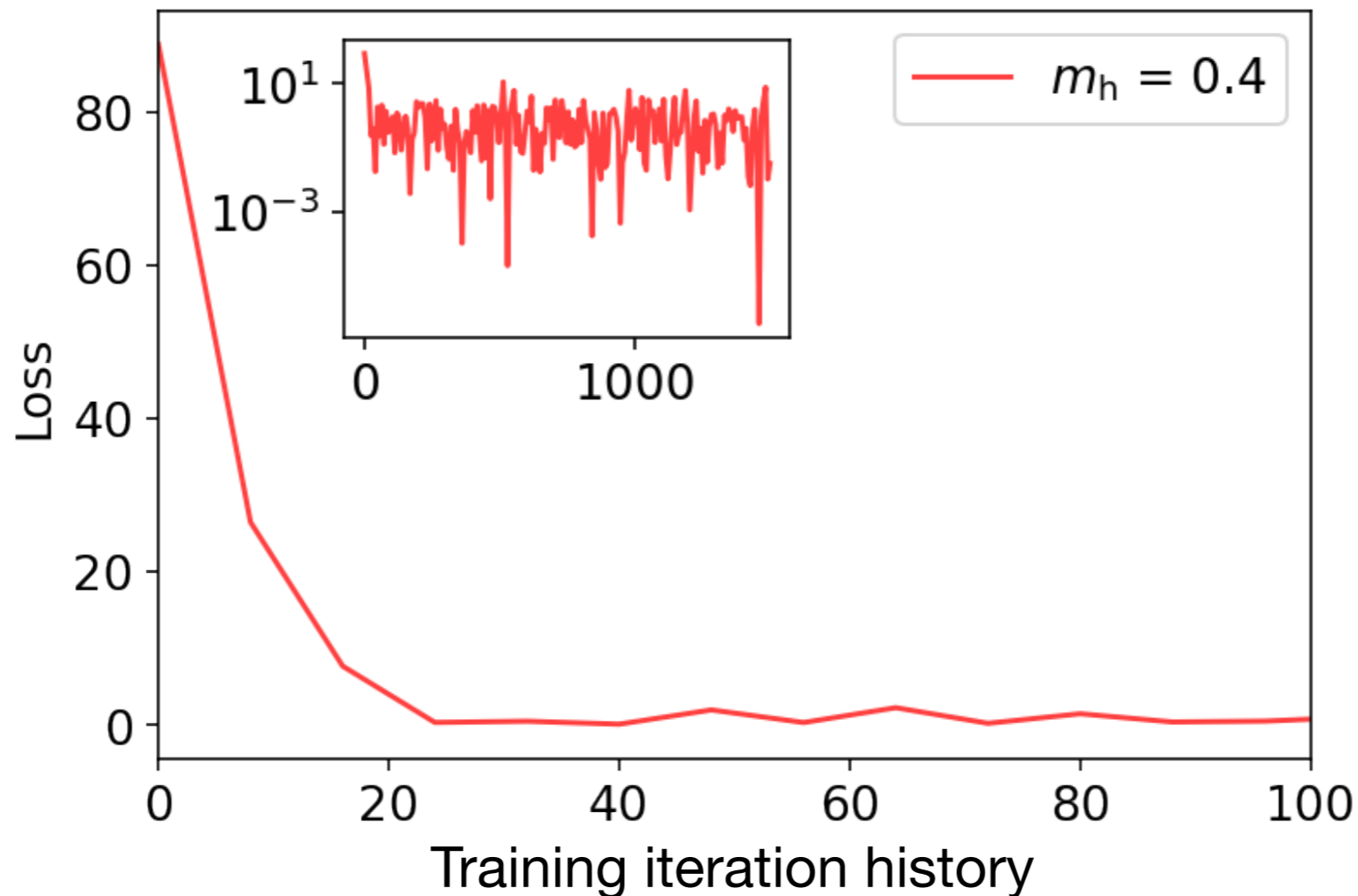
AT+ (in prep)

Details (skip)

Results: Loss decreases along with the training

arXiv: 2103.11965

Loss function: $L_{\theta}[U] = \frac{1}{2} \left| S_{\theta}[U, \phi] - S[U, \phi] \right|^2, \sim -\log(\text{reweighting factor})$



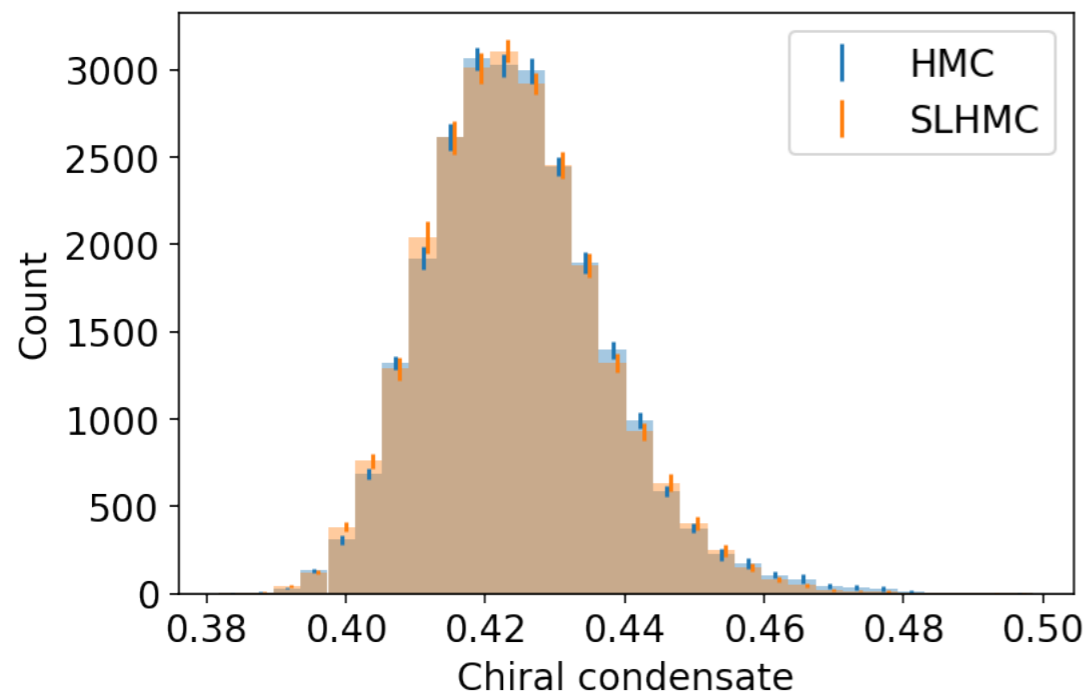
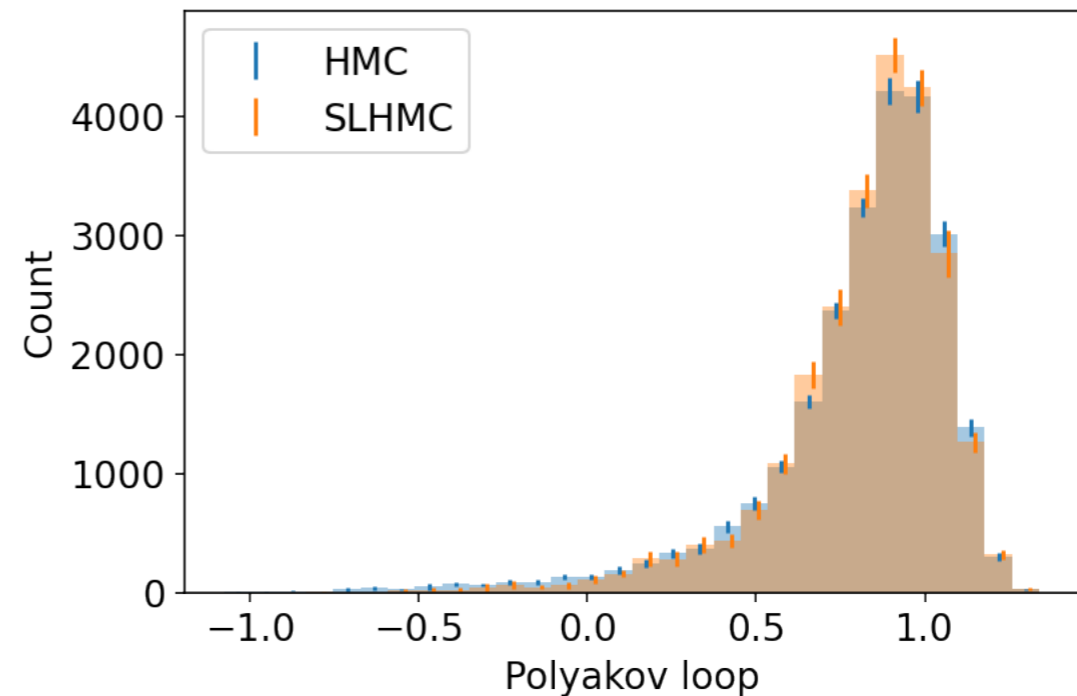
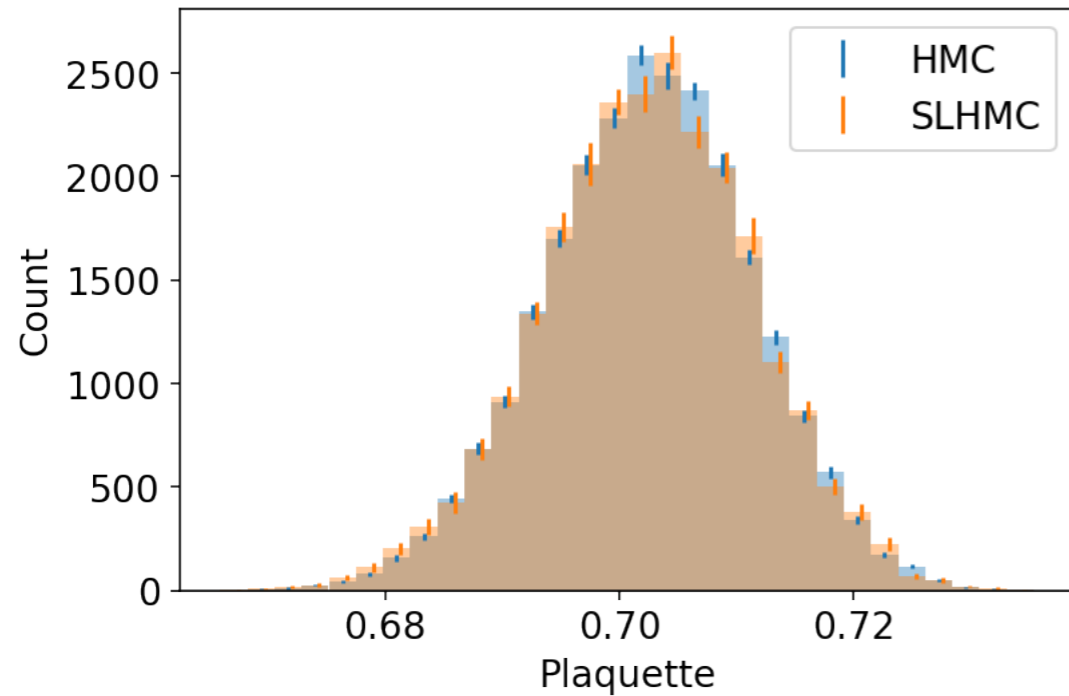
Without training, $e^{(-L)} \ll 1$, this means that candidate with approximated action never accept.

After training, $e^{(-L)} \sim 1$, and we get practical acceptance rate!

Application for the staggered in 4d

Results are consistent with each other

arXiv: 2103.11965



| Expectation value | | |
|-------------------|-------------------|-----------|
| Algorithm | Observable | Value |
| HMC | Plaquette | 0.7025(1) |
| SLHMC | Plaquette | 0.7023(2) |
| HMC | Polyakov loop | 0.82(1) |
| SLHMC | Polyakov loop | 0.83(1) |
| HMC | Chiral condensate | 0.4245(5) |
| SLHMC | Chiral condensate | 0.4241(5) |

Acceptance = 40%

Other architecture: Flow based sample algorithm

Related works

Gradient flow as a trivializing map

Trivializing map for lattice QCD has been demanded...

$$\langle \mathcal{O} \rangle = \frac{1}{Z} \int \cdots \int \prod_{x \in 100} \prod_{y \in 100} \prod_{z \in 100} \prod_{t \in 100} d\phi_{x,y,z,t} e^{-S(\phi)} \mathcal{O}[\phi_{x,y,z,t}]$$

$$\tilde{\phi} = \mathcal{F}_\tau(\phi) \quad \text{Flow equation (change variable)}$$

If the solution satisfies $S(\mathcal{F}_\tau(\phi)) + \ln \det(\text{Jacobian}) = \sum_n \tilde{\phi}_n^2$,

Flow based sampling algorithm

Normalizing flow ~ Change of variables

Simplest example: Box Muller

$$\int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy e^{-\frac{1}{2}x^2 - \frac{1}{2}y^2} = \frac{1}{2} \int_0^{2\pi} d\theta \int_0^1 dz$$

Original integral: hard
Easy

Change of variables $\begin{cases} z = e^{-\frac{1}{2}(x^2+y^2)} \\ \tan \theta = y/x \end{cases}$

Point: Make problem easier with change of variables (make the measure flat)

RHS is flat measure
→ We can sample like right eq.

$$\begin{cases} \xi_1 \sim (0, 2\pi) \\ \xi_2 \sim (0, 1) \end{cases}$$

We can reconstruct a "field config" x, y for original theory like right eq.

$$\begin{cases} x = r \cos \theta & \theta = \xi_1 \\ y = r \sin \theta & r = \sqrt{-2 \log \xi_2} \end{cases}$$

A change of variable which $D\phi e^{-S[\phi]}$ makes flat = **Trivializing map**

Related works

Gradient flow as a trivializing map

Trivializing map for lattice QCD has been demanded...

$$\langle \mathcal{O} \rangle = \frac{1}{Z} \int \cdots \int \prod_{x \in 100} \prod_{y \in 100} \prod_{z \in 100} \prod_{t \in 100} d\phi_{x,y,z,t} e^{-S(\phi)} \mathcal{O}[\phi_{x,y,z,t}]$$

$$\tilde{\phi} = \mathcal{F}_\tau(\phi) \quad \text{Flow equation (change variable)}$$

If the solution satisfies $S(\mathcal{F}_\tau(\phi)) + \ln \det(\text{Jacobian}) = \sum_n \tilde{\phi}_n^2$,

$$\langle \mathcal{O} \rangle = \frac{1}{Z} \int \cdots \int \prod_{x \in 100} \prod_{y \in 100} \prod_{z \in 100} \prod_{t \in 100} d\tilde{\phi} \mathcal{O}[\mathcal{F}_\tau(\phi)] e^{-\sum \tilde{\phi}_n^2}$$

It becomes Gaussian integral! Easy to evaluate!!

However, the Jacobian cannot evaluate easily, so it is not practical.
Life is hard.

Related works

Flow based algorithm = neural net represented flow algorithm

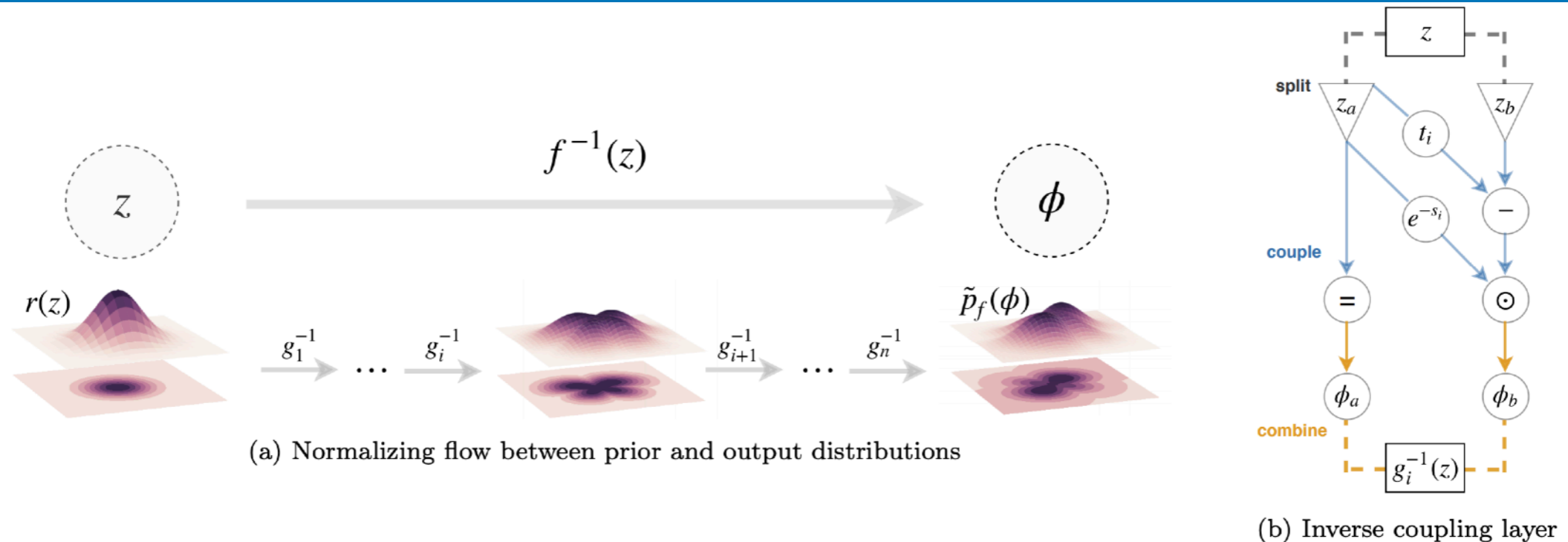


FIG. 1: In (a), a normalizing flow is shown transforming samples z from a prior distribution $r(z)$ to samples ϕ distributed according to $\tilde{p}_f(\phi)$. The mapping $f^{-1}(z)$ is constructed by composing inverse coupling layers g_i^{-1} as defined in Eq. (10) in terms of neural networks s_i and t_i and shown diagrammatically in (b). By optimizing the neural networks within each coupling layer, $\tilde{p}_f(\phi)$ can be made to approximate a distribution of interest, $p(\phi)$.

MIT + Google brain 2019~

Train a neural net as a “flow” $\tilde{\phi} = \mathcal{F}(\phi)$

If it is well approximated, we can sample from a Gaussian

It can be done “Normalizing flow” (Real Non-volume preserving map)

Moreover, Jacobian is tractable!

Related works

Flow based algorithm = neural net represented flow algorithm

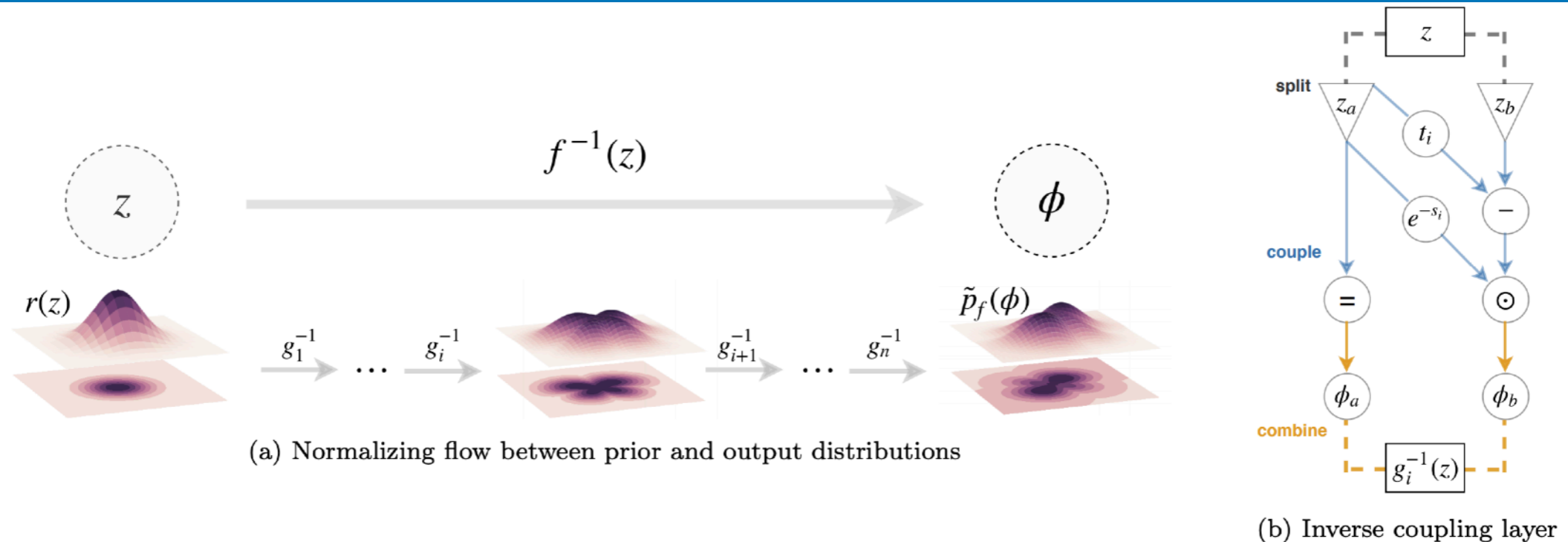


FIG. 1: In (a), a normalizing flow is shown transforming samples z from a prior distribution $r(z)$ to samples ϕ distributed according to $\tilde{p}_f(\phi)$. The mapping $f^{-1}(z)$ is constructed by composing inverse coupling layers g_i^{-1} as defined in Eq. (10) in terms of neural networks s_i and t_i and shown diagrammatically in (b). By optimizing the neural networks within each coupling layer, $\tilde{p}_f(\phi)$ can be made to approximate a distribution of interest, $p(\phi)$.

MIT + Google brain 2019~

Their sampling strategy

- Sampling from Gaussian
- Apply an inverse trivializing map (neural network)
- QFT configurations + Tractable Jacobian (by even-odd strategy)
- Metropolis-Hastings test (Detailed balance), **exact!**

Flow based sampling algorithm

Flow based ML for QFT

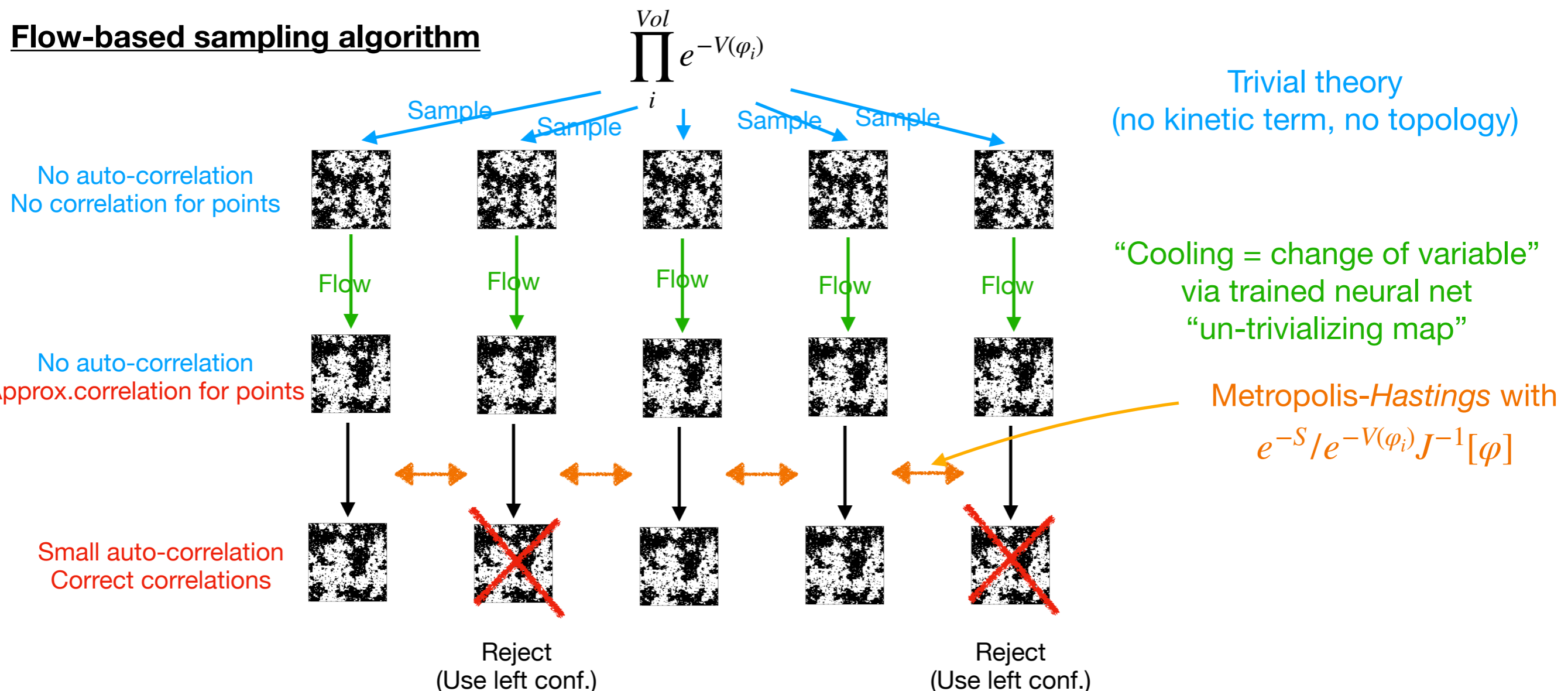
MIT + Deepmind + ...

$$\int D\phi e^{-S[\phi]} O[\phi] \propto \prod_i \int d\varphi_i e^{-V(\varphi_i)} J^{-1}[\varphi] O[F[\varphi]]$$

Original integral: hard

Easy

Flow-based sampling algorithm





GomalizingFlow.jl: A Julia package for Flow-based sampling algorithm for lattice field theory

Akio Tomiya

*Faculty of Technology and Science, International Professional University of Technology,
3-3-1, Umeda, Kita-ku, Osaka, 530-0001, Osaka, Japan*

Satoshi Terasaki

AtelierArith, 980-0004, Miyagi, Japan

A public code for
Flow-based sampling
algorithm
not only 2d but also 3d, 4d

Combinational-convolution for flow-based sampling algorithm

Akio Tomiya

International Professional University of Technology in Osaka
Faculty of Technology and Science,
International Professional University of Technology,
3-3-1, Umeda, Kita-ku, Osaka, 530-0001, Osaka, Japan
akio@yukawa.kyoto-u.ac.jp

Satoshi Terasaki

AtelierArith
980-0004 Miyagi Japan
s.terasaki@atelier-arith.jp

Improvement of
convolution for the flow
has been reported in
NurIPS2022
workshop

Summary

1. What and why QCD/lattice QCD?

1. Problem: Long auto-correlation

2. Lattice QCD + Machine learning

1. Trainable smearing + SLHMC = adaptive reweighting

2. Flow-based sampling algorithm

$$\frac{dU_{\mu}^{(t)}(n)}{dt} = \mathcal{G}^{\bar{\theta}}(U_{\mu}^{(t)}(n)) = \text{MLNN}$$
